On Strongly Regular Graphs, the Friendship Theorem, Lovász Function, and Shannon Capacity of Graphs

Igal Sason, Technion - Israel Institute of Technology

Algorithmic Graph Theory Seminar Series
April 28, 2025

Graph Spectrum

Throughout this presentation,

- G = (V(G), E(G)) is a finite, undirected, and simple graph of order |V(G)| = n and size |E(G)| = m.
- A = A(G) is the adjacency matrix of the graph.
- The eigenvalues of A are given in decreasing order by

$$\lambda_{\max}(\mathsf{G}) = \lambda_1(\mathsf{G}) \ge \lambda_2(\mathsf{G}) \ge \ldots \ge \lambda_n(\mathsf{G}) = \lambda_{\min}(\mathsf{G}).$$
 (1.1)

• The *spectrum* of G is a multiset that consists of all the eigenvalues of A, including their multiplicities.

Orthogonal Representation of Graphs

Definition 1.1

Let G be a finite, undirected and simple graph.

An orthogonal representation of G in \mathbb{R}^d

$$i \in V(G) \mapsto \mathbf{u}_i \in \mathbb{R}^d$$

such that

$$\mathbf{u}_i^{\mathrm{T}}\mathbf{u}_j = 0, \quad \forall \{i, j\} \notin \mathsf{E}(\mathsf{G}).$$

An orthonormal representation of G: $\|\mathbf{u}_i\| = 1$ for all $i \in V(G)$.

Orthogonal Representation of Graphs

Definition 1.1

Let G be a finite, undirected and simple graph.

An orthogonal representation of G in \mathbb{R}^d

$$i \in V(G) \mapsto \mathbf{u}_i \in \mathbb{R}^d$$

such that

$$\mathbf{u}_i^{\mathrm{T}}\mathbf{u}_j = 0, \quad \forall \{i, j\} \notin \mathsf{E}(\mathsf{G}).$$

An orthonormal representation of G: $\|\mathbf{u}_i\| = 1$ for all $i \in V(G)$.

In an orthogonal representation of a graph G:

- non-adjacent vertices: mapped to orthogonal vectors;
- adjacent vertices: not necessarily mapped to non-orthogonal vectors.

Lovász ϑ -function

Let G be a finite, undirected and simple graph.

The Lovász ϑ -function of G is defined as

$$\vartheta(\mathsf{G}) \triangleq \min_{\mathbf{u}, \mathbf{c}} \max_{i \in \mathsf{V}(\mathsf{G})} \frac{1}{\left(\mathbf{c}^{\mathrm{T}} \mathbf{u}_{i}\right)^{2}},$$
(1.2)

where the minimum is taken over

- ullet all orthonormal representations $\{{f u}_i:i\in {\sf V}({\sf G})\}$ of ${\sf G},$ and
- all unit vectors c.

The unit vector c is called the *handle* of the orthonormal representation.

Lovász ϑ -function

Let G be a finite, undirected and simple graph.

The Lovász ϑ -function of G is defined as

$$\vartheta(\mathsf{G}) \triangleq \min_{\mathbf{u}, \mathbf{c}} \max_{i \in \mathsf{V}(\mathsf{G})} \frac{1}{\left(\mathbf{c}^{\mathrm{T}} \mathbf{u}_{i}\right)^{2}},$$
(1.2)

where the minimum is taken over

- ullet all orthonormal representations $\{{f u}_i:i\in V({\sf G})\}$ of ${\sf G},$ and
- all unit vectors c.

The unit vector c is called the *handle* of the orthonormal representation.

$$|\mathbf{c}^{\mathrm{T}}\mathbf{u}_i| \leq \|\mathbf{c}\| \|\mathbf{u}_i\| = 1 \implies \vartheta(\mathsf{G}) \geq 1,$$

with equality if and only if G is a complete graph.

◆□▶ ◆□▶ ◆壹▶ ◆壹▶ 壹 めなべ

An Orthonormal Representation of a Pentagon

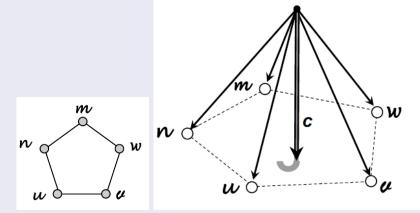


Figure 1: A 5-cycle graph and its orthonormal representation (also known as Lovász umbrella). Calculation shows that $\vartheta(C_5) = \sqrt{5}$ (Lovász, 1979).

Lovász ϑ -function (Cont.)

- **A** is the $n \times n$ adjacency matrix of G $(n \triangleq |V(G)|)$;
- \mathbf{J}_n is the all-ones $n \times n$ matrix;
- ullet \mathcal{S}^n_+ is the set of all $n \times n$ positive semidefinite matrices.

Semidefinite program (SDP), with strong duality, for computing $\vartheta(G)$:

```
 \begin{cases} \text{maximize Trace}(\mathbf{B}\,\mathbf{J}_n) \\ \text{subject to} \\ \mathbf{B} \in \mathcal{S}^n_+, \ \text{Trace}(\mathbf{B}) = 1, \\ A_{i,j} = 1 \ \Rightarrow \ B_{i,j} = 0, \quad i,j \in [n]. \end{cases}
```

Computational complexity: \exists algorithm (based on the ellipsoid method) that numerically computes $\vartheta(\mathsf{G})$, for every graph G , with precision of r decimal digits, and polynomial-time in n and r.

Lovász ϑ -function (Cont.)

Let $\alpha(G)$, $\omega(G)$, and $\chi(G)$ denote the independence number, clique number, and chromatic number of a graph G. Then,

Sandwich theorem:

$$\alpha(\mathsf{G}) \le \vartheta(\mathsf{G}) \le \chi(\overline{\mathsf{G}}),$$
(1.3)

$$\omega(\mathsf{G}) \le \vartheta(\overline{\mathsf{G}}) \le \chi(\mathsf{G}).$$
 (1.4)

Lovász ϑ -function (Cont.)

Let $\alpha(G)$, $\omega(G)$, and $\chi(G)$ denote the independence number, clique number, and chromatic number of a graph G. Then,

Sandwich theorem:

$$\alpha(\mathsf{G}) \le \vartheta(\mathsf{G}) \le \chi(\overline{\mathsf{G}}),$$
 (1.3)

$$\omega(\mathsf{G}) \le \vartheta(\overline{\mathsf{G}}) \le \chi(\mathsf{G}).$$
 (1.4)

- Computational complexity:
 - $\alpha(G)$, $\omega(G)$, and $\chi(G)$ are NP-hard problems.
 - ▶ However, the numerical computation of $\vartheta(G)$ is in general feasible by convex optimization (SDP problem).

Hoffman-Lovasz bound and edge-transitive regular graphs

Theorem 1.2 (Lovász, 1979)

Let G be d-regular of order n. Then,

$$\vartheta(\mathsf{G}) \le -\frac{n\,\lambda_n(\mathsf{G})}{d - \lambda_n(\mathsf{G})},$$
(1.5)

with equality if G is edge-transitive.

Strongly Regular Graphs

Let G be a d-regular graph of order n. It is a $strongly\ regular\ graph\ (SRG)$ if there exist nonnegative integers λ and μ such that

- ullet Every pair of adjacent vertices have exactly λ common neighbors;
- \bullet Every pair of distinct and non-adjacent vertices have exactly μ common neighbors.

Such a strongly regular graph is said to belong to the family $srg(n, d, \lambda, \mu)$.

Theorem: Adjacency Spectrum of Strongly Regular Graphs

Let G be a connected strongly regular graph in the family $\operatorname{srg}(n,d,\lambda,\mu)$ (i.e., $\mu>0$). Then, its adjacency spectrum consists of three distinct eigenvalues, where the largest eigenvalue is given by $\lambda_1(\mathsf{G})=d$ with multiplicity 1, and the other two distinct eigenvalues of its adjacency matrix are given by

$$p_{1,2} = \frac{1}{2} \left(\lambda - \mu \pm \sqrt{(\lambda - \mu)^2 + 4(d - \mu)} \right),$$
 (1.6)

with the respective multiplicities

$$m_{1,2} = \frac{1}{2} \left(n - 1 \mp \frac{2d + (n-1)(\lambda - \mu)}{\sqrt{(\lambda - \mu)^2 + 4(d - \mu)}} \right).$$
 (1.7)

◄□▶◀圖▶◀불▶◀불▶ 불 ∽Q҈

Theorem 1.3 (Bounds on Lovász function of Regular Graphs, I.S., '23)

Let G be a d-regular graph of order n, which is a non-complete and non-empty graph. Then, the following bounds hold for the Lovász ϑ -function of G and its complement $\overline{\mathsf{G}}$:

1)

$$\frac{n-d+\lambda_2(\mathsf{G})}{1+\lambda_2(\mathsf{G})} \le \vartheta(\mathsf{G}) \le -\frac{n\lambda_n(\mathsf{G})}{d-\lambda_n(\mathsf{G})}.$$
 (1.8)

- Equality holds in the leftmost inequality if \overline{G} is both vertex-transitive and edge-transitive, or if G is a strongly regular graph;
- Equality holds in the rightmost inequality if G is edge-transitive, or if G is a strongly regular graph.

I. Sason, Technion, Israel April 28, 2025 11/47

Cont. of Theorem 1.3

2)

$$1 - \frac{d}{\lambda_n(\mathsf{G})} \le \vartheta(\overline{\mathsf{G}}) \le \frac{n(1 + \lambda_2(\mathsf{G}))}{n - d + \lambda_2(\mathsf{G})}.$$
 (1.9)

- Equality holds in the leftmost inequality if G is both vertex-transitive and edge-transitive, or if G is a strongly regular graph;
- Equality holds in the rightmost inequality if \overline{G} is edge-transitive, or if G is a strongly regular graph.

Cont. of Theorem 1.3

2)

$$1 - \frac{d}{\lambda_n(\mathsf{G})} \le \vartheta(\overline{\mathsf{G}}) \le \frac{n(1 + \lambda_2(\mathsf{G}))}{n - d + \lambda_2(\mathsf{G})}.$$
 (1.9)

- Equality holds in the leftmost inequality if G is both vertex-transitive and edge-transitive, or if G is a strongly regular graph;
- Equality holds in the rightmost inequality if \overline{G} is edge-transitive, or if G is a strongly regular graph.

A Common Sufficient Condition

All inequalities hold with equality if G is strongly regular. (Recall that the graph G is strongly regular if and only if \overline{G} is so).

I. Sason, Technion, Israel April 28, 2025 12 / 47

Lovász Function of Strongly Regular Graphs (I.S., '23)

Let G be a strongly regular graph in the family $srg(n, d, \lambda, \mu)$. Then,

$$\vartheta(\mathsf{G}) = \frac{n(t+\mu-\lambda)}{2d+t+\mu-\lambda},\tag{1.10}$$

$$\vartheta(\overline{\mathsf{G}}) = 1 + \frac{2d}{t + \mu - \lambda},\tag{1.11}$$

where

$$t \triangleq \sqrt{(\mu - \lambda)^2 + 4(d - \mu)}. (1.12)$$

Lovász Function of Strongly Regular Graphs (I.S., '23)

Let G be a strongly regular graph in the family $srg(n, d, \lambda, \mu)$. Then,

$$\vartheta(\mathsf{G}) = \frac{n(t+\mu-\lambda)}{2d+t+\mu-\lambda},\tag{1.10}$$

$$\vartheta(\overline{\mathsf{G}}) = 1 + \frac{2d}{t + \mu - \lambda},\tag{1.11}$$

where

$$t \triangleq \sqrt{(\mu - \lambda)^2 + 4(d - \mu)}. (1.12)$$

New Relation for Strongly Regular Graphs

$$\vartheta(\mathsf{G})\,\vartheta(\overline{\mathsf{G}}) = n,\tag{1.13}$$

holding not only for all vertex-transitive graphs (Lovász '79), but also for all strongly regular graphs (that are not necessarily vertex-transitive).

In general, we have $\vartheta(\mathsf{G})\,\vartheta(\overline{\mathsf{G}})\geq n$ (Lovász, 1979).

The Lovász ϑ -function of strongly regular graphs (SRGs) is uniquely determined by its four parameters (n, d, λ, μ) .

I. Sason, Technion, Israel April 28, 2025 14 /

The Lovász ϑ -function of strongly regular graphs (SRGs) is uniquely determined by its four parameters (n, d, λ, μ) .

This is interesting because strongly regular graphs with the same set of parameters are not necessarily isomorphic.

The Lovász ϑ -function of strongly regular graphs (SRGs) is uniquely determined by its four parameters (n, d, λ, μ) .

This is interesting because strongly regular graphs with the same set of parameters are not necessarily isomorphic.

Example: Chang Graphs

- Chang graphs are three non-isomorphic strongly regular graphs with parameters srg(28,12,6,4).
- These graphs are not vertex-transitive and also not edge-transitive.
- The clique numbers of these 3 graphs are 5, 6, 6.

The Lovász ϑ -function of strongly regular graphs (SRGs) is uniquely determined by its four parameters (n, d, λ, μ) .

This is interesting because strongly regular graphs with the same set of parameters are not necessarily isomorphic.

Example: Chang Graphs

- Chang graphs are three non-isomorphic strongly regular graphs with parameters srg(28,12,6,4).
- These graphs are not vertex-transitive and also not edge-transitive.
- The clique numbers of these 3 graphs are 5, 6, 6.
- Nevertheless, they have the same Lovász ϑ -function, being equal to 4. The Lovász ϑ -function of the complements, all srg(28,15,6,10), is 7.
- Note that, indeed, $\vartheta(\mathsf{G})\,\vartheta(\overline{\mathsf{G}})=28$ for these three graphs, although they are not vertex-transitive (but SRGs).

Strongly regular graphs that belong to the same family $\operatorname{srg}(n,d,\lambda,\mu)$, where $\mu>0$, are connected and cospectral graphs. Although these graphs are not necessarily isomorphic, their Lovász ϑ -functions are identical.

Strongly regular graphs that belong to the same family $\operatorname{srg}(n,d,\lambda,\mu)$, where $\mu>0$, are connected and cospectral graphs. Although these graphs are not necessarily isomorphic, their Lovász ϑ -functions are identical.

Question

Are there any pairs of connected and cospectral graphs with distinct Lovász ϑ -functions?

Strongly regular graphs that belong to the same family $\operatorname{srg}(n,d,\lambda,\mu)$, where $\mu>0$, are connected and cospectral graphs. Although these graphs are not necessarily isomorphic, their Lovász ϑ -functions are identical.

Question

Are there any pairs of connected and cospectral graphs with distinct Lovász ϑ -functions?

The next result gives a positive answer to this question.

Theorem 1.5 (A result with an explicit construction (I.S, 2024))

For every even integer $n \geq 14$, it is constructively proven that there exist connected, irregular, cospectral, and nonisomorphic graphs on n vertices, with the following properties:

- They are jointly cospectral with respect to their adjacency, Laplacian, signless Laplacian, and normalized Laplacian matrices.
- They share identical independence, clique, and chromatic numbers.
- They are distinguished by their Lovász ϑ -functions.

We next provide an original proof of the following celebrated theorem by Erdös, Rényi and Sós (1966), based on our expression for the Lovász ϑ -function of strongly regular graphs.

Theorem 1.6 (Friendship Theorem)

Let G be a finite graph in which any two distinct vertices have a single common neighbor. Then, G has a vertex adjacent to every other vertex.

We next provide an original proof of the following celebrated theorem by Erdös, Rényi and Sós (1966), based on our expression for the Lovász ϑ -function of strongly regular graphs.

Theorem 1.6 (Friendship Theorem)

Let G be a finite graph in which any two distinct vertices have a single common neighbor. Then, G has a vertex adjacent to every other vertex.

A Human Interpretation of Theorem 1.6

Assume there is a party with n people, where every two people have precisely one common friend in that party. Theorem 1.6 asserts that one of these people is everybody's friend.

Remark 1 (On the Friendship Theorem - Theorem 1.6)

- The windmill graph (see Figure 2) has the desired property, and it turns out to be the only one graph with that property.
- The friendship theorem does not hold for infinite graphs.



Figure 2: Windmill graph.

Alternative Proof of Theorem 1.6 (I.S., 25)

Suppose the assertion is false, and G is a counterexample — a finite graph in which any two distinct vertices have a single common neighbor, yet no vertex in G is adjacent to all other vertices. A contradiction is obtained by the following proof outline:

- It is shown that the graph is regular.
- It is then shown that the graph is strongly regular srg(n, k, 1, 1).
- By assumption, k = 1 is excluded.
- If k=0 or k=2, then $\mathsf{G}=\mathsf{K}_1$ or $\mathsf{G}=\mathsf{K}_3$, respectively, which satisfy the assertion of the theorem. Hence, next assume that $k\geq 3$.
- By the theorem hypothesis, it follows that $\omega(\mathsf{G}) = \chi(\mathsf{G}) = 3$.
- By the sandwich theorem $\omega(\mathsf{G}) \leq \vartheta(\overline{\mathsf{G}}) \leq \chi(\mathsf{G})$, so $\vartheta(\overline{\mathsf{G}}) = 3$.
- Based on the expression for the Lovász ϑ -function $\vartheta(\overline{\mathsf{G}}) = 1 + \frac{k}{\sqrt{k-1}}.$
- This leads to a contradiction for all $k \geq 3$.

4□ > 4酉 > 4 를 > 4 를 > 9 €

The sandwich theorem for the Lovász ϑ -function applied to strongly regular graphs gives the following result.

Corollary 1.7 (Bounds on Parameters of SRGs)

Let G be a strongly regular graph in the family $srg(n, d, \lambda, \mu)$. Then,

$$\alpha(\mathsf{G}) \le \left\lfloor \frac{n(t+\mu-\lambda)}{2d+t+\mu-\lambda} \right\rfloor$$
(1.14)

$$\omega(\mathsf{G}) \le 1 + \left\lfloor \frac{2d}{t + \mu - \lambda} \right\rfloor,$$
 (1.15)

$$\chi(\mathsf{G}) \ge 1 + \left\lceil \frac{2d}{t + \mu - \lambda} \right\rceil,\tag{1.16}$$

$$\chi(\overline{\mathsf{G}}) \ge \left| \frac{n(t+\mu-\lambda)}{2d+t+\mu-\lambda} \right|,$$
(1.17)

with

$$t \triangleq \sqrt{(\mu - \lambda)^2 + 4(d - \mu)}. (1.18)$$

Examples: Bounds on Parameters of SRGs

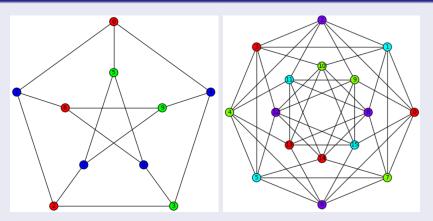


Figure 3: The Petersen graph is srg(10,3,0,1) (left), and the Shrikhande graph is srg(16,6,2,2) (right). Their chromatic numbers are 3 and 4, respectively.

Schläfli Graph

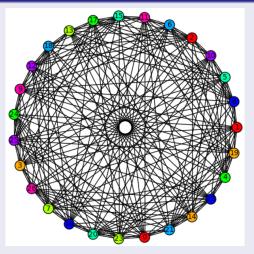


Figure 4: Schläfli graph is srg(27, 16, 10, 8) with chromatic number $\chi(\mathsf{G}) = 9$.

40 140 140 15 15 15 10 10

Examples: Bounds on Parameters of SRGs (Cont.)

ullet Let G_1 be the Petersen graph. Then, the bounds on the independence, clique, and chromatic numbers of G are tight:

$$\alpha(\mathsf{G}_1) = 4, \quad \omega(\mathsf{G}_1) = 2, \quad \chi(\mathsf{G}_1) = 3.$$
 (1.19)

② The bounds on the chromatic numbers of the Schläfli graph (G_2) , Shrikhande graph (G_3) and Hall-Janko graph (G_4) are tight:

$$\chi(\mathsf{G}_2) = 9, \quad \chi(\mathsf{G}_3) = 4, \quad \chi(\mathsf{G}_4) = 10.$$
 (1.20)

- \odot For the Shrikhande graph (G_3) ,
 - ▶ the bound on its independence number is also tight: $\alpha(\mathsf{G}_3) = 4$,
 - its upper bound on its clique number is, however, not tight (it is equal to 4, and $\omega(\mathsf{G}_3)=3$).

Strong Product of Graphs

Let G and H be two graphs. The strong product $G \boxtimes H$ is a graph with

- vertex set: $V(G \boxtimes H) = V(G) \times V(H)$,
- two distinct vertices (g,h) and (g',h') in $G \boxtimes H$ are adjacent if one of the following three conditions hold:

 - **3** $\{g, g'\} \in E(G) \text{ and } \{h, h'\} \in E(H).$

Strong products are commutative and associative.

Strong Product of Graphs

Let G and H be two graphs. The strong product $G \boxtimes H$ is a graph with

- vertex set: $V(G \boxtimes H) = V(G) \times V(H)$,
- two distinct vertices (g,h) and (g',h') in $G \boxtimes H$ are adjacent if one of the following three conditions hold:

 - $\{g,g'\} \in \mathsf{E}(\mathsf{G}) \text{ and } h = h',$

Strong products are commutative and associative.

Strong Powers of Graphs

Let

$$\mathsf{G}^{\boxtimes k} \triangleq \underbrace{\mathsf{G} \boxtimes \ldots \boxtimes \mathsf{G}}_{\mathsf{G} \text{ appears } k \text{ times}}, \quad k \in \mathbb{N}$$
 (1.21)

denote the k-fold strong power of a graph G.

Theorem 1.8 (chromatic number of strong product of SRGs (I.S., '23))

Let G_1, \ldots, G_k be strongly regular graphs $\operatorname{srg}(n_\ell, d_\ell, \lambda_\ell, \mu_\ell)$ for $\ell \in [k]$ (they need not be distinct). Then, the chromatic number of their strong product satisfies

$$\left[\prod_{\ell=1}^{k} \left(1 + \frac{2d_{\ell}}{t_{\ell} + \mu_{\ell} - \lambda_{\ell}}\right)\right] \leq \chi(\mathsf{G}_{1} \boxtimes \ldots \boxtimes \mathsf{G}_{k}) \leq \prod_{\ell=1}^{k} \chi(\mathsf{G}_{k}), (1.22)$$

where $\{t_\ell\}_{\ell=1}^k$ in the leftmost term is given by

$$t_{\ell} \triangleq \sqrt{(\lambda_{\ell} - \mu_{\ell})^2 + 4(d_{\ell} - \mu_{\ell})}, \quad \ell \in [k]. \tag{1.23}$$

The above lower bound is also larger than or equal to the product of the clique numbers of the factors $\{G_\ell\}_{\ell=1}^k$.

Example: Chromatic Numbers of Strong Products

Let

$$\mathsf{G} \in \mathsf{srg}(27, 16, 10, 8), \quad \mathsf{H} \in \mathsf{srg}(16, 6, 2, 2), \quad \mathsf{J} \in \mathsf{srg}(100, 36, 14, 12)$$

be the Schläfli, Shrikhande, and Hall-Janko graphs, respectively. The upper and lower bounds (in the previous slide) coincide here: for all integers $k_1,k_2,k_3\geq 0$,

$$\chi(\mathsf{G}^{\boxtimes k_1} \boxtimes \mathsf{H}^{\boxtimes k_2} \boxtimes \mathsf{J}^{\boxtimes k_3}) = 9^{k_1} 4^{k_2} 10^{k_3}.$$
(1.24)

For comparison, the lower bound that is given by the product of the clique numbers of each factor is looser, and it is equal to $6^{k_1}3^{k_2}4^{k_3}$.

Shannon Capacity of a Graph

- A discrete channel consists of
 - a finite input set X;
 - ightharpoonup a (possibly infinite) output set ${\cal Y}$
 - ▶ a non-empty fan-out set $S_x \subseteq \mathcal{Y}$ for every $x \in \mathcal{X}$.

Shannon Capacity of a Graph

- A discrete channel consists of
 - a finite input set X;
 - ightharpoonup a (possibly infinite) output set ${\cal Y}$
 - ▶ a non-empty fan-out set $S_x \subseteq \mathcal{Y}$ for every $x \in \mathcal{X}$.
- In each channel use, a sender transmits an input $x \in \mathcal{X}$ and a receiver receives an arbitrary output in \mathcal{S}_x .

Shannon Capacity of a Graph

- A discrete channel consists of
 - a finite input set X;
 - ightharpoonup a (possibly infinite) output set ${\cal Y}$
 - ▶ a non-empty fan-out set $S_x \subseteq \mathcal{Y}$ for every $x \in \mathcal{X}$.
- In each channel use, a sender transmits an input $x \in \mathcal{X}$ and a receiver receives an arbitrary output in \mathcal{S}_x .
- Shannon (1956) initiated the study of the maximum amount (rate) of information that a channel can communicate without error.

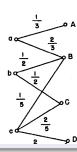


THE ZERO ERROR CAPACITY OF A NOISY CHANNEL

Claude E. Shannon
Bell Telephone Laboratories, Murray Hill, New Jersey
Massachusetts Institute of Technology, Cambridge, Mass.

Abstract

The zero error capacity Co of a noisy channel is defined as the least upper bound of rates at which it is possible to transmit information with zero probability of error. Various properties of Co are studied; upper and lower bounds and methods of evaluation of Co are given. Inequalities are obtained for the Co relating to the "sum" and "product" of two given channels. The analogous problem of zero error capacity Coy for a channel with a feedback link is considered. It is shown that while the ordinary capacity of a memoryless channel with feedback is equal to that of the same channel without feedback, the zero error capacity may be greater. A solution is given to the problem of evaluating Cop.



28 / 47

A discrete memoryless channel is represented by a confusion graph G:

• V(G) represent the symbols of the input alphabet to that channel.

A discrete memoryless channel is represented by a confusion graph G:

- V(G) represent the symbols of the input alphabet to that channel.
- E(G): Two distinct vertices in G are adjacent if the corresponding two input symbols (say $x, x' \in \mathcal{X}$) are not distinguishable by the channel.

$$V(G) = \mathcal{X},$$

$$E(G) = \{ \{x, x'\} : x, x' \in \mathcal{X}, x \neq x', S_x \cap S_{x'} \neq \emptyset \}.$$

(Both distinct input symbols can result in the same output.)

The largest number of inputs a channel can communicate without error in a single use is $\alpha(G)$ (the independence number of G).

The largest number of inputs a channel can communicate without error in a single use is $\alpha(G)$ (the independence number of G):

- The sender and the receiver agree in advance on an independent set $\mathcal I$ of a maximum size $\alpha(\mathsf G)$.
- ullet The sender transmits only inputs in \mathcal{I} .
- ullet Every received output is in the fan-out set of exactly one input in $\mathcal{I}.$
 - \Rightarrow the receiver can correctly determine the transmitted input.

ullet Consider a transmission of k-length strings over a channel.

- ullet Consider a transmission of k-length strings over a channel.
 - ▶ The channel is used $k \ge 1$ times;
 - ▶ The sender transmits a sequence $x_1 \dots x_k$;
 - lacktriangle The receiver receives a sequence $y_1 \dots y_k$ of outputs, where

$$y_i \in \mathcal{S}_{x_i}, \quad i = 1, \dots, k.$$

- ullet Consider a transmission of k-length strings over a channel.
 - ▶ The channel is used $k \ge 1$ times;
 - ▶ The sender transmits a sequence $x_1 \dots x_k$;
 - ▶ The receiver receives a sequence $y_1 \dots y_k$ of outputs, where

$$y_i \in \mathcal{S}_{x_i}, \quad i = 1, \dots, k.$$

- k uses of the channel are viewed as a single use of a larger channel:
 - its input set is \mathcal{X}^k , and its output set is \mathcal{Y}^k .
 - ▶ The fan-out set of $(x_1, ..., x_k) \in \mathcal{X}^k$ is the Cartesian product

$$\mathcal{S}_{x_1} \times \dots \mathcal{S}_{x_k}$$
.

• The k-th confusion graph is the k-fold strong power of G:

$$\mathsf{G}^{\boxtimes k} \triangleq \mathsf{G} \boxtimes \ldots \boxtimes \mathsf{G}. \tag{2.1}$$

• The k-th confusion graph is the k-fold strong power of G:

$$\mathsf{G}^{\boxtimes k} \triangleq \mathsf{G} \boxtimes \ldots \boxtimes \mathsf{G}. \tag{2.1}$$

• $\alpha(G^{\boxtimes k})$ is the max. number of k-length strings at the channel input that are distinguishable by the channel (error-free communication).

• The k-th confusion graph is the k-fold strong power of G:

$$\mathsf{G}^{\boxtimes k} \triangleq \mathsf{G} \boxtimes \ldots \boxtimes \mathsf{G}. \tag{2.1}$$

- $\alpha(G^{\boxtimes k})$ is the max. number of k-length strings at the channel input that are distinguishable by the channel (error-free communication).
- The maximum information rate per symbol that is achievable by using input strings of length k is equal to

$$\frac{1}{k}\log\alpha(\mathsf{G}^{\boxtimes k}) = \log\sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}, \quad k \in \mathbb{N}.$$
 (2.2)

• The Shannon capacity of a graph G is defined to be the supremum of the maximum information rate over k (the length k of the input strings can be made as large as we wish):

$$\Theta(\mathsf{G}) = \sup_{k \in \mathbb{N}} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}$$

$$= \lim_{k \to \infty} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}.$$
(2.3)

• The Shannon capacity of a graph G is defined to be the supremum of the maximum information rate over k (the length k of the input strings can be made as large as we wish):

$$\Theta(\mathsf{G}) = \sup_{k \in \mathbb{N}} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}$$

$$= \lim_{k \to \infty} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}.$$
(2.3)

The last equality holds by Fekete's Lemma: the sequence $\{\alpha(\mathsf{G}^{\boxtimes k})\}_{k=1}^\infty$ is super-multiplicative, i.e.,

$$\alpha(\mathsf{G}^{\boxtimes (k_1+k_2)}) \ge \alpha(\mathsf{G}^{\boxtimes k_1}) \ \alpha(\mathsf{G}^{\boxtimes k_2}). \tag{2.4}$$

I. Sason, Technion, Israel April 28, 2025 33 / 47

• The Shannon capacity of a graph G is defined to be the supremum of the maximum information rate over k (the length k of the input strings can be made as large as we wish):

$$\Theta(\mathsf{G}) = \sup_{k \in \mathbb{N}} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}$$

$$= \lim_{k \to \infty} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})}.$$
(2.3)

The last equality holds by Fekete's Lemma: the sequence $\{\alpha(\mathsf{G}^{\boxtimes k})\}_{k=1}^\infty$ is super-multiplicative, i.e.,

$$\alpha(\mathsf{G}^{\boxtimes (k_1+k_2)}) \ge \alpha(\mathsf{G}^{\boxtimes k_1}) \ \alpha(\mathsf{G}^{\boxtimes k_2}). \tag{2.4}$$

Alas, the Shannon capacity can be rarely computed exactly !

On the Computability of the Shannon Capacity of Graphs

• The Shannon capacity of a graph can be rarely computed exactly. ©

34 / 47

On the Computability of the Shannon Capacity of Graphs

• The Shannon capacity of a graph can be rarely computed exactly. © N. Alon and E. Lubetzky (IEEE T-IT, May 2006).

On the Computability of the Shannon Capacity of Graphs

- The Shannon capacity of a graph can be rarely computed exactly. © N. Alon and E. Lubetzky (IEEE T-IT, May 2006).
- However, the Lovász ϑ -function of a graph is a computable (and sometimes tight) upper bound on the Shannon capacity. \odot



IEEE TRANSACTIONS ON INFORMATION THEORY, VOL. IT-25, NO. 1, JANUARY 1979

On the Shannon Capacity of a Graph

LÁSZLÓ LOVÁSZ

Abstract—It is proved that the Shannon zero-error capacity of the pentagon is $\sqrt{5}$. The method is then generalized to obtain upper bounds on the capacity of an arbitrary graph. A well-characterized, and in a sense easily computable, function is introduced which bounds the capacity from above and equals the capacity in a large number of cases. Several results are obtained on the capacity of special graphs; for example, the Petersen graph has capacity four and a self-complementary graph with n points and with a vertex-transitive automorphism group has capacity \sqrt{n} .

A general upper bound on $\Theta(G)$ was also given in [6] (this bound was discussed in detail by Rosenfeld [5]). We assign nonnegative weights w(x) to the vertices x of G such that

$$\sum_{x \in C} w(x) \le 1$$

for every complete subgraph C in G; such an assignment is called a *fractional vertex packing*. The maximum of

I. Sason, Technion, Israel April 28, 2025 35 / 47

Lovász Bound on the Shannon Capacity of Graphs (1979)

Theorem 2.1

For every finite, simple and undirected graph G,

$$\Theta(\mathsf{G}) \le \vartheta(\mathsf{G}).$$
 (2.5)

Lovász Bound on the Shannon Capacity of Graphs (1979)

Theorem 2.1

For every finite, simple and undirected graph G,

$$\Theta(\mathsf{G}) \le \vartheta(\mathsf{G}). \tag{2.5}$$

Proof

$$\Theta(\mathsf{G}) = \lim_{k \to \infty} \sqrt[k]{\alpha(\mathsf{G}^{\boxtimes k})} \tag{2.6}$$

$$\leq \lim_{k \to \infty} \sqrt[k]{\vartheta(\mathsf{G}^{\boxtimes k})} \tag{2.7}$$

$$=\vartheta(\mathsf{G})\tag{2.8}$$

where the last equality holds since $\vartheta(\mathsf{G}^{\boxtimes k}) = \vartheta(\mathsf{G})^k$ forall $k \in \mathbb{N}$.

- イロト イ掛ト イミト イミト - 夏

Theorem 2.2 (Lovász, 1979)

Let G be a self-complementary and vertex-transitive graph on n vertices. Then,

$$\Theta(\mathsf{G}) = \sqrt{n} = \vartheta(\mathsf{G}),\tag{2.9}$$

$$\alpha(\mathsf{G}\boxtimes\mathsf{G})=n. \tag{2.10}$$

Theorem 2.2 (Lovász, 1979)

Let G be a self-complementary and vertex-transitive graph on n vertices. Then,

$$\Theta(\mathsf{G}) = \sqrt{n} = \vartheta(\mathsf{G}),\tag{2.9}$$

$$\alpha(\mathsf{G}\boxtimes\mathsf{G})=n. \tag{2.10}$$

Theorem 2.3 (Lovász, 1979)

Let G = K(n,k) be a non-empty Kneser graph $(n \ge 2k)$. Then,

$$\alpha(\mathsf{G}) = \Theta(\mathsf{G}) = \vartheta(\mathsf{G}) = \binom{n-1}{k-1}.$$
 (2.11)

I. Sason, Technion, Israel

Theorem 2.2 (Lovász, 1979)

Let G be a self-complementary and vertex-transitive graph on n vertices. Then.

$$\Theta(\mathsf{G}) = \sqrt{n} = \vartheta(\mathsf{G}),\tag{2.9}$$

$$\alpha(\mathsf{G}\boxtimes\mathsf{G})=n. \tag{2.10}$$

Theorem 2.3 (Lovász, 1979)

Let G = K(n,k) be a non-empty Kneser graph $(n \ge 2k)$. Then,

$$\alpha(\mathsf{G}) = \Theta(\mathsf{G}) = \vartheta(\mathsf{G}) = \binom{n-1}{k-1}.$$
 (2.11)

Theorem 2.4 (I.S., '24)

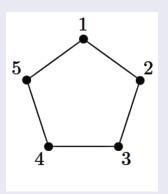
The same result in Theorem 2.2 for self-complementary vertex-transitive graphs also holds for self-complementary strongly regular graphs.

I. Sason, Technion, Israel April 28, 2025 37/47

Example: Shannon Capacity of a 5-Cycle Graph (Lovász, 1979)

The pentagon (5-cycle) C_5 is self-complementary and vertex-transitive, so

$$\Theta(\mathsf{C}_5) = \sqrt{5} = \vartheta(\mathsf{C}_5), \quad \alpha(\mathsf{G} \boxtimes \mathsf{G}) = 5.$$
 (2.12)



$\alpha(\mathsf{C}_5 \boxtimes \mathsf{C}_5) = 5$

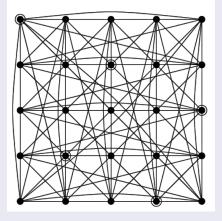


Figure 5: $C_5 \boxtimes C_5$. Independent set: $\{(1,1), (2,3), (3,5), (4,2), (5,4)\}$.

Theorem 2.5 (On the Shannon capacity of graphs, I.S. '24)

Let ${\sf G}$ be an undirected and simple graph on n vertices.

1 If G is a vertex-transitive or strongly regular graph, then

$$\alpha(\mathsf{G}\boxtimes\overline{\mathsf{G}})=\Theta(\mathsf{G}\boxtimes\overline{\mathsf{G}})=\vartheta(\mathsf{G}\boxtimes\overline{\mathsf{G}})=n. \tag{2.12}$$

- ② If G is a conference graph, then $\vartheta(G) = \sqrt{n}$.
- **③** If G is a self-complementary graph with $\alpha(G) = k$, then

$$\sqrt{n} \le \Theta(\mathsf{G}) \le 16 \, n^{\frac{k-1}{k+1}}.\tag{2.13}$$

 If G is self-complementary and either vertex-transitive or strongly regular, then

$$\Theta(\mathsf{G}) = \sqrt{n} = \vartheta(\mathsf{G}), \qquad \sqrt{\alpha(\mathsf{G} \boxtimes \mathsf{G})} = \Theta(\mathsf{G}).$$
 (2.14)

Hence, the minimum Shannon capacity among all self-complementary graphs of a fixed order n is achieved by such graphs, and it is \sqrt{n} .

Lovász ϑ -function $\vartheta(\mathsf{G})$

- A is the $n \times n$ adjacency matrix of G $(n \triangleq |V(G)|)$;
- \mathbf{J}_n is the all-ones $n \times n$ matrix;
- ullet \mathcal{S}^n_+ is the set of all $n \times n$ positive semidefinite matrices.

Semidefinite program (SDP), with strong duality, for computing $\vartheta(G)$:

```
 \begin{cases} \text{maximize Trace}(\mathbf{B}\,\mathbf{J}_n) \\ \text{subject to} \\ \mathbf{B} \in \mathcal{S}^n_+, \ \text{Trace}(\mathbf{B}) = 1, \\ A_{i,j} = 1 \ \Rightarrow \ B_{i,j} = 0, \quad i,j \in [n]. \end{cases}
```

Computational complexity: \exists algorithm (based on the ellipsoid method) that numerically computes $\vartheta(\mathsf{G})$, for every graph G , with precision of r decimal digits, and polynomial-time in n and r.

Schrijver's ϑ -function $\vartheta'(\mathsf{G})$

- **A** is the $n \times n$ adjacency matrix of G $(n \triangleq |V(G)|)$;
- \mathbf{J}_n is the all-ones $n \times n$ matrix;
- ullet \mathcal{S}^n_+ is the set of all $n \times n$ positive semidefinite matrices.

Semidefinite program (SDP), with strong duality, for computing $\vartheta'(G)$:

```
\begin{aligned} & \text{maximize Trace}(\mathbf{B}\,\mathbf{J}_n) \\ & \text{subject to} \\ & \begin{cases} \mathbf{B} \in \mathcal{S}^n_+, & \text{Trace}(\mathbf{B}) = 1, \\ B_{i,j} \geq 0, & i,j \in [n], \\ A_{i,j} = 1 \ \Rightarrow \ B_{i,j} = 0, & i,j \in [n]. \end{cases} \end{aligned}
```

Computational complexity: \exists algorithm (based on the ellipsoid method) that numerically computes $\vartheta'(\mathsf{G})$, for every graph G , with precision of r decimal digits, and polynomial-time in n and r.

Theorem 2.6

For every graph G,

$$\alpha(\mathsf{G}) \le \vartheta'(\mathsf{G}) \le \vartheta(\mathsf{G}).$$
 (2.15)

Theorem 2.6

For every graph G,

$$\alpha(\mathsf{G}) \le \vartheta'(\mathsf{G}) \le \vartheta(\mathsf{G}).$$
 (2.15)

Proof

The leftmost inequality in (2.15) holds by selecting a feasible solution in the maximization problem for $\vartheta'(\mathsf{G})$ as follows.

- Let \mathcal{I} be a largest independent set in G, and let $\mathcal{I} = \{i_1, \dots, i_\ell\} \subseteq [n]$ with $\ell = \alpha(\mathsf{G})$.
- Define ${\bf B}$ to be the $n \times n$ symmetric matrix whose elements are given by $B_{i,j} \triangleq \frac{1}{\alpha({\bf G})}$ whenever $i,j \in \mathcal{I}$, and $B_{i,j} \triangleq 0$ otherwise.
- \Rightarrow **B** is indeed a positive semidefinite matrix whose trace is equal to 1, and the objective function is then equal to $\alpha(\mathsf{G})$.

The rightmost inequality in (2.15) is due to the additional constraint in the optimization problem for $\vartheta'(\mathsf{G})$, as compared to one for $\vartheta(\mathsf{G})$.

Question

Can the upper bound on the Shannon capacity,

$$\Theta(\mathsf{G}) \leq \vartheta(\mathsf{G})$$

be improved to

$$\Theta(\mathsf{G}) \leq \vartheta'(\mathsf{G})$$
?

Question

Can the upper bound on the Shannon capacity,

$$\Theta(\mathsf{G}) \leq \vartheta(\mathsf{G})$$

be improved to

$$\Theta(\mathsf{G}) \leq \vartheta'(\mathsf{G})$$
?

Our work resolves this query regarding the variant of the ϑ -function by Schrijver (1978). We show, by a counterexample, that

$$\Theta(\mathsf{G}) \not\leq \vartheta'(\mathsf{G})$$

i.e., the ϑ -function variant by Schrijver does not possess the property of the Lovász ϑ -function of forming an upper bound on the Shannon capacity of a graph.

Let G be the Gilbert graph on 32 vertices, where

$$\mathsf{V}(\mathsf{G}) = \{0,1\}^5, \qquad \mathsf{E}(\mathsf{G}) = \Big\{\underline{u},\underline{v} \in \{0,1\}^5: \ 1 \leq d_{\mathsf{H}}(\underline{u},\underline{v}) \leq 2\Big\},$$

so, every two vertices are adjacent if and only if the Hamming distance of their corresponding 5-tuples binary vectors is either 1 or 2.

I. Sason, Technion, Israel April 28, 2025 44/

Let G be the Gilbert graph on 32 vertices, where

$$\mathsf{V}(\mathsf{G}) = \{0,1\}^5, \qquad \mathsf{E}(\mathsf{G}) = \Big\{\underline{u},\underline{v} \in \{0,1\}^5: \ 1 \leq d_{\mathsf{H}}(\underline{u},\underline{v}) \leq 2\Big\},$$

so, every two vertices are adjacent if and only if the Hamming distance of their corresponding 5-tuples binary vectors is either 1 or 2.

• G is 15-regular, vertex-transitive, edge-transitive, distance-regular.

I. Sason, Technion, Israel April 28, 2025 44 /

Let G be the Gilbert graph on 32 vertices, where

$$V(G) = \{0, 1\}^5, \qquad E(G) = \{\underline{u}, \underline{v} \in \{0, 1\}^5: 1 \le d_H(\underline{u}, \underline{v}) \le 2\},$$

so, every two vertices are adjacent if and only if the Hamming distance of their corresponding 5-tuples binary vectors is either 1 or 2.

- G is 15-regular, vertex-transitive, edge-transitive, distance-regular.
- The complement G is 16-regular, vertex-transitive, but not edge-transitive nor distance-regular.

I. Sason, Technion, Israel April 28, 2025 44/

Let G be the Gilbert graph on 32 vertices, where

$$\mathsf{V}(\mathsf{G}) = \{0,1\}^5, \qquad \mathsf{E}(\mathsf{G}) = \Big\{\underline{u},\underline{v} \in \{0,1\}^5: \ 1 \leq d_H(\underline{u},\underline{v}) \leq 2\Big\},$$

so, every two vertices are adjacent if and only if the Hamming distance of their corresponding 5-tuples binary vectors is either 1 or 2.

- G is 15-regular, vertex-transitive, edge-transitive, distance-regular.
- The complement G is 16-regular, vertex-transitive, but not edge-transitive nor distance-regular.
- ullet $\alpha(G)=4$. An example of such a maximal independent set of G:

$$\big\{(1,0,0,1,0),\;(0,1,1,1,0),\;(0,0,0,0,1),\;(1,1,1,0,1)\big\}.$$

Let G be the Gilbert graph on 32 vertices, where

$$\mathsf{V}(\mathsf{G}) = \{0,1\}^5, \qquad \mathsf{E}(\mathsf{G}) = \Big\{\underline{u},\underline{v} \in \{0,1\}^5: \ 1 \leq d_H(\underline{u},\underline{v}) \leq 2\Big\},$$

so, every two vertices are adjacent if and only if the Hamming distance of their corresponding 5-tuples binary vectors is either 1 or 2.

- G is 15-regular, vertex-transitive, edge-transitive, distance-regular.
- The complement \overline{G} is 16-regular, vertex-transitive, but not edge-transitive nor distance-regular.
- $\quad \bullet \ \, \alpha(\mathsf{G}) = 4. \ \, \text{An example of such a maximal independent set of G:} \\ \big\{ (1,0,0,1,0), \ (0,1,1,1,0), \ (0,0,0,0,1), \ (1,1,1,0,1) \big\}.$
- ullet Solving the SDP problem for $\vartheta'(\mathsf{G})$ gives

$$\vartheta'(\mathsf{G}) = 4 = \alpha(\mathsf{G}).$$

• G is 15-regular and edge-transitive on 32 vertices, with $\lambda_{\min}(\mathsf{G})=-3$, so by Theorem 1.2,

$$\vartheta(\mathsf{G}) = -\frac{n\lambda_{\min}(\mathsf{G})}{d(\mathsf{G}) - \lambda_{\min}(\mathsf{G})} = \frac{32\cdot3}{15+3} = 5\frac{1}{3}.$$

I. Sason, Technion, Israel

• G is 15-regular and edge-transitive on 32 vertices, with $\lambda_{\min}(G)=-3$, so by Theorem 1.2,

$$\vartheta(\mathsf{G}) = -\frac{n\lambda_{\min}(\mathsf{G})}{d(\mathsf{G}) - \lambda_{\min}(\mathsf{G})} = \frac{32 \cdot 3}{15 + 3} = 5\frac{1}{3}.$$

• Hence, for this graph,

$$4 = \alpha(\mathsf{G}) = \vartheta'(\mathsf{G}) < \vartheta(\mathsf{G}) = 5\frac{1}{3},$$

so $\vartheta'(G)$ coincides with the independence number of G, and it is strictly smaller than $\vartheta(G)$.

• G is 15-regular and edge-transitive on 32 vertices, with $\lambda_{\min}(G)=-3$, so by Theorem 1.2,

$$\vartheta(\mathsf{G}) = -\frac{n\lambda_{\min}(\mathsf{G})}{d(\mathsf{G}) - \lambda_{\min}(\mathsf{G})} = \frac{32 \cdot 3}{15 + 3} = 5\frac{1}{3}.$$

• Hence, for this graph,

$$4 = \alpha(\mathsf{G}) = \vartheta'(\mathsf{G}) < \vartheta(\mathsf{G}) = 5\frac{1}{3},$$

so $\vartheta'(G)$ coincides with the independence number of G, and it is strictly smaller than $\vartheta(G)$.

It can be verified that

$$\alpha(\mathsf{G}\boxtimes\mathsf{G})=20,$$

and the strong product graph $G \boxtimes G$ has 368,640 such maximal independent sets of size 20.

4 D > 4 D > 4 E > 4 E > E 900

• An example of a maximal independent set (of size 20) for $G \boxtimes G$:

```
\{((1,1,0,0,0),(1,1,1,1,1)),
                                ((1,0,1,0,0),(1,1,0,0,0)),
 ((0, 1, 1, 0, 0), (0, 0, 1, 1, 0)),
                                ((1,1,1,0,0),(0,0,0,0,1)),
 ((1,0,0,1,0),(0,0,1,0,1)),
                                ((0,1,0,1,0),(1,0,0,0,0)),
 ((1, 1, 0, 1, 0), (0, 1, 0, 1, 0)),
                                ((0,0,1,1,0),(0,1,0,1,1)),
 ((1,0,1,1,0),(1,0,1,1,0)),
                                ((0,1,1,1,0),(1,1,1,0,1)),
 ((1,0,0,0,1),(0,0,0,1,0)),
                                ((0,1,0,0,1),(0,1,0,0,1)),
 ((1, 1, 0, 0, 1), (1, 0, 1, 0, 0)),
                                ((0,0,1,0,1),(1,0,1,0,1)),
 ((1,0,1,0,1),(0,1,1,1,1)),
                                ((0,1,1,0,1),(1,1,0,1,0)),
 ((0,0,0,1,1),(1,1,1,1,0)),
                                ((1,0,0,1,1),(1,1,0,0,1)),
                                ((0,0,1,1,1),(0,0,0,0,0)).
 ((0,1,0,1,1),(0,0,1,1,1)),
```

• An example of a maximal independent set (of size 20) for $G \boxtimes G$:

$$\big\{ ((1,1,0,0,0),(1,1,1,1,1)), \quad ((1,0,1,0,0),(1,1,0,0,0)), \\ ((0,1,1,0,0),(0,0,1,1,0)), \quad ((1,1,1,0,0),(0,0,0,0,1)), \\ ((1,0,0,1,0),(0,0,1,0,1)), \quad ((0,1,0,1,0),(1,0,0,0,0)), \\ ((1,1,0,1,0),(0,1,0,1,0)), \quad ((0,0,1,1,0),(0,1,0,1,1)), \\ ((1,0,1,1,0),(1,0,1,1,0)), \quad ((0,1,1,1,0),(1,1,1,0,1)), \\ ((1,0,0,0,1),(0,0,0,1,0)), \quad ((0,1,0,0,1),(0,1,0,0,1)), \\ ((1,1,0,0,1),(1,0,1,0,0)), \quad ((0,0,1,0,1),(1,0,1,0,1)), \\ ((1,0,1,0,1),(0,1,1,1,1)), \quad ((0,1,1,0,1),(1,1,0,1,0)), \\ ((0,0,0,1,1),(1,1,1,1,0)), \quad ((1,0,0,1,1),(1,1,0,0,1)), \\ ((0,0,0,1,1),(0,0,1,1,1)), \quad ((0,0,1,1,1),(0,0,0,0,0)) \big\}.$$

Consequently, we get

$$\Theta(\mathsf{G}) \ge \sqrt{\alpha(\mathsf{G} \boxtimes \mathsf{G})} = \sqrt{20} > 4 = \vartheta'(\mathsf{G}).$$

4□ ▶ 4団 ▶ 4 豆 ▶ 4 豆 ▶ 豆 め Q ()

I. Sason, Technion, Israel April 28, 2025 46 / 47

Journal Papers

This talk presents in part results from our recent papers:

- I.S., "Observations on the Lovász ϑ-function, graph capacity, eigenvalues, and strong products," Entropy, vol. 25, no. 1, paper 104, pp. 1–40, January 2023. https://doi.org/10.3390/e25010104
- I.S., "Observations on graph invariants with the Lovász θ-function," AIMS Mathematics, vol. 9, pp. 15385–15468, April 2024. https://doi.org/10.3934/math.2024747
- I.S., "On strongly regular graphs and the friendship theorem," Mathematics, vol. 13, paper 970, pp. 1–21, March 2025. https://doi.org/10.3390/math13060970