

Parameter Estimation Based on Noisy Chaotic Signals in the Weak-Noise Regime

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Twisted Modulation

Consider the AWGN channel,

$$y_i = x_i + z_i, \quad i = 1, 2, \dots, n,$$

where $z_i \sim \mathcal{N}(0, \sigma^2)$ are i.i.d. and

$$\mathbf{x} = (x_1, \dots, x_n) = f_n(\theta), \quad \|\mathbf{x}\|^2 \leq nQ$$

$\theta \in [0, 1]$ being a parameter to be estimated at the receiver by $\hat{\theta} = g_n(\mathbf{y})$.

How well can we estimate θ if we have the freedom to choose both the modulator $f_n(\cdot)$ and the estimator, $g_n(\cdot)$?

Twisted Modulation (Cont'd)

- The “waveform communication” problem (Wozencraft & Jacobs, ‘65).
- Source/channel coding: Shannon-Kotel’nikov ('49; '59).
- Hekland ('07); Floor ('08+); Hekland, Floor & Ramstad ('09, '23).
- Estimation theory; Cohn, ('70), Burnashev ('84, '85).
- Linear modulation – **Fisher efficient**, but **limited**.
- Nonlinear modulation – **flexible**, but suffers a **threshold effect**.
- Most of the literature: **total** MSE.
- Reasonable to separate $\Pr\{\text{anomaly}\}$ and weak-noise errors.
- Köken, Günduz & Tuncel ('17): $\min MSE$ s.t. $\Pr\{\text{anomaly}\} \leq \epsilon$.
- Merhav ('19): exponential $\Pr\{\text{anomaly}\}$ + matching converse.
- Merhav ('20): extension to parameter vectors.
- This work: modulators based on **chaotic dynamical systems**.

Motivations for Studying Chaotic Modulators

- Sensitivity to initial conditions – good weak-noise estimation.
- High degree of flexibility in the design.
- \exists mature theoretical understanding about chaos.
- Computationally easy to generate the modulated signal.
- \exists computationally efficient estimation algorithms (halving method).
- Good estimation of initial condition is also good for filtering.

Related Work

Modulators based on chaotic systems have been investigated extensively during the last 3 decades from a variety of aspects:

- Upper/lower bounds on MSE.
- Numerical aspects.
- Algorithmic efficiency.
- System optimization.
- Applications in Turbo coding, hybrid coding, spread spectrum, MIMO, etc.

Chen ('96); Chen & Wornell ('98); Cong *et al.* ('99); Drake ('98); Eckmann & Ruelle ('85); Hen & Merhav ('04); Kay & Nagesha ('95); Kennedy & Kolumbán ('00); Leung *et al.* ('06); Pantaleón *et al.* ('03); Papadopoulos & Wornell ('95); Wallinger ('13); Wang *et al.* ('99); Xie *et al.* ('09); Yu *et al.* ('18),

Objectives

The purpose this work is to carry out a systematic study of modulators that are based on certain class of chaotic systems, from the perspective of earlier work on fundamental limits of general modulators:

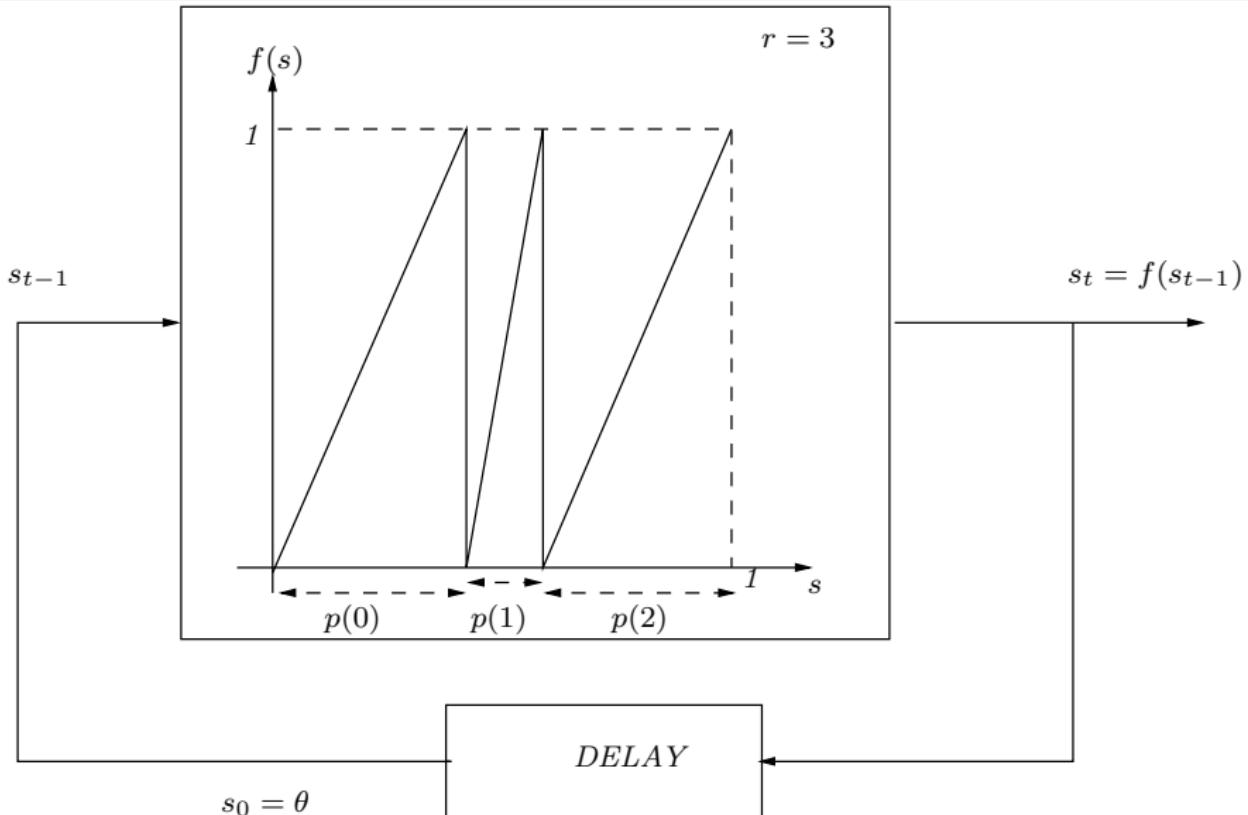
Given a certain parametric family of modulators, find the one with the best weak-noise error performance s. t. $\Pr\{\text{anomaly}\} \rightarrow 0$.

We consider a general error performance criterion,

$$\sup_{\theta \in [0,1]} \mathbf{E} \left\{ \rho(\hat{\theta} - \theta) \middle| \text{no anomaly} \right\} \quad \rho(\cdot) \text{ convex}$$

and avoid the use of the Cramér-Rao lower bound, which is problematic for systems with discontinuous mappings.

The Chaotic Dynamical System



Formulation

Select a positive integer r and a **probability vector**,
 $P = \{p(0), p(1), \dots, p(r-1)\}$. Define:

$$F(x) = \sum_{x'=0}^{x-1} p(x'); \quad F(0) = 0, \quad F(r) = 1.$$

Given $s \in [0, 1]$, let $\phi(s)$ be the value of $x \in \{0, 1, \dots, r-1\}$ such that

$$F(x) \leq s < F(x+1), \quad \phi(1) = 1.$$

The non-linear dynamical system is defined by the recursion:

$$\begin{aligned} x_t &= \phi(s_{t-1}), & s_0 = \theta & \text{itinerary sequence} \\ s_t &= \frac{s_{t-1} - F(x_t)}{p(x_t)} & & \text{state sequence} \end{aligned}$$

for $t = 1, 2, \dots$. The channel input is

$$u_t = \sqrt{12Q} \left(s_t - \frac{1}{2} \right).$$

System Properties

1. Reconstruction of s_0 from x_1, x_2, \dots :

$$s_0 = \sum_{t=1}^{\infty} F(x_t) \prod_{i=1}^{t-1} p(x_i) \stackrel{\triangle}{=} \sum_{t=1}^{\infty} G(x_t) \prod_{i=1}^t p(x_i)$$

Example: if $P = (1/r, \dots, 1/r)$,

$$s_0 = \sum_{t=1}^{\infty} x_t r^{-t} = 0.x_1 x_2 \dots$$

2. X_t as a random process (with application to process simulation): If $S_0 \sim \text{Unif}[0, 1]$, then $S_t \sim \text{Unif}[0, 1]$ and $\{X_t\}$ is a DMS governed by P . (Easy extension to arbitrary processes with memory).

3. Lyapunov exponent:

$$\lambda \stackrel{\triangle}{=} \lim_{n \rightarrow \infty} \frac{1}{n} \mathbf{E} \left\{ \ln \left| \frac{\partial s_n}{\partial s_0} \right| \right\} = H \quad \text{the entropy of } P.$$

System Properties (Cont'd)

4. Length of signal locus:

$$L_n = \int_0^1 \left\| \frac{\partial}{\partial \theta} \mathbf{u}(\theta) \right\| \cdot d\theta \doteq r^n.$$

Therefore $\ln r$ must be $< C = \frac{1}{2} \ln(1 + \gamma)$, $\gamma = \frac{Q}{\sigma^2}$ to keep $\Pr\{\text{anomaly}\}$ small.

5. Autocorrelation:

$$R_S(k) = \mathbf{E}\{S_0 S_k\} = \frac{1}{4} + \frac{1}{12} \cdot \left(\sum_{x=0}^{r-1} p^2(x) \right)^{|k|}.$$

$$R_U(k) = \mathbf{E}\{U_0 U_k\} = Q \cdot \left(\sum_{x=0}^{r-1} p^2(x) \right)^{|k|}.$$

System Properties (Cont'd)

6. Channel input-output mutual information:

$$C_0 = \lim_{n \rightarrow \infty} \frac{I(U^n; Y^n)}{n} \leq \frac{1}{2} \ln \frac{A}{\sigma^2} \triangleq C_1$$

where

$$\frac{A}{\sigma^2} = \frac{1}{2} \left[1 + \gamma + q^2(1 - \gamma) + \sqrt{(1 + \gamma^2)(1 - q^2)^2 + 2\gamma(1 - q^4)} \right]$$

and

$$q = \sum_{x=0}^{r-1} p^2(x).$$

7. Ergodic property:

The Lebesgue measure of the set:

$$\left\{ s_0 : \left| \frac{1}{n} \sum_{t=1}^n u_t u_{t+k} - R_U(k) \right| \leq \epsilon \right\}$$

tends to unity as $n \rightarrow \infty$.

General Lower Bound

Suppose that $\rho(\cdot)$ has the following property: $\forall c > 0$, $\rho(e^{-nc}) \doteq e^{-n\zeta(c)}$ with $\zeta(c) > 0$.

For example, if $\rho(\epsilon) = |\epsilon|^a$, then $\zeta(c) = a \cdot c$.

Theorem [Merhav 2019]: For any modulator and estimator,

$$\sup_{0 \leq \theta \leq 1} \mathbf{E} \left\{ \rho(\hat{\theta} - \theta) \middle| \text{no anomaly} \right\} \doteq \exp \left\{ -n\zeta \left(\frac{1}{2} \ln \gamma \right) \right\}$$

for $\gamma \gg 1$.

Asymptotically achievable by uniform quantization of θ followed by capacity-achieving channel coding.

Lower Bound for the Class of Chaotic Modulators

Theorem: For any chaotic modulator from the class defined and any estimator,

$$\begin{aligned} & \sup_{0 \leq \theta \leq 1} \mathbf{E} \left\{ \rho(\hat{\theta} - \theta) \middle| \text{no anomaly} \right\} \\ & \geq \exp \left(-n\zeta \left[\min \left\{ C_1, \frac{1}{2} \ln \gamma - \frac{1}{2} \ln \left(\frac{2\pi e}{12} \right) \right\} \right] \right) \end{aligned}$$

for $\gamma \gg 1$.

The term $\frac{1}{2} \ln \left(\frac{2\pi e}{12} \right)$ = shaping loss since $\{u_t\}$ is distributed uniformly rather than normally.

$C_1 < \frac{1}{2} \ln \gamma$ = loss associated with the fact that $\{u_t\}$ has memory.

We could have increased C_1 up to C by decreasing $q = \sum_x p^2(x) \geq \frac{1}{r}$, but recall that r is limited by $\ln r \leq C$.

Feeding the Channel by the Itinerary Signal?

At first glance it seems counterintuitive that the itinerary sequence, $\{x_t\}$ could do a better job than the state sequence, $\{s_t\}$ (or $\{u_t\}$) since $\{x_t\}$ is a quantized version of $\{s_t\}$:

$$x_t = \phi(s_{t-1}), \quad F(x_t) \leq s_{t-1} < F(x_t + 1).$$

However, recall that $\{s_t\}$ is generated from s_0 which in turn can be expressed in terms of (x_1, x_2, \dots) . Thus, (x_1, x_2, \dots) and (s_1, s_2, \dots) include exactly the same information about s_0 .

- For large n , (x_1, x_2, \dots, x_n) and (s_1, s_2, \dots, s_n) and include almost the same information about s_0 .
- If $S_0 \sim \text{Unif}[0, 1]$, $\{X_t\}$ is an i.i.d. process governed by P . No loss due to input memory.
- No limitation on r : select P to approximate the capacity-achieving input distribution, $\mathcal{N}(0, Q)$.

Proposed Modulation Scheme

- Given $\theta \in [0, 1]$, quantize it to θ_i using a fine grid of $M = e^{n(C-\epsilon)}$ points and a random mapping of the grid onto itself, $\eta_i = \psi(\theta_i)$.
- Let $s_0 = \eta_i$ be the initial state of the modulator.
- Transmit \mathbf{x} over the channel.
- Decode $\hat{\eta}_i$.
- $\hat{\theta}_i = \psi^{-1}(\hat{\eta}_i)$.

If the decoding is correct (which is the case w.h.p.), there is only a quantization error:

$$\rho(\theta_i - \theta) \leq \rho\left(\frac{1}{2M}\right) = \rho(e^{-n(C-\epsilon)}) = e^{-n\zeta(C-\epsilon)}.$$

Decoding error = anomaly.