

On Row-by-Row Coding for 2-D Constraints

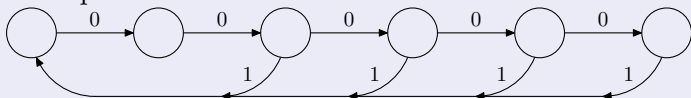
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Graph Representable Constraint

1-D Constraints

- Let $G(V, E, L)$ be an edge labeled graph, $L : E \rightarrow \Sigma$.
- Example:



- $S = S(G)$ is the set of all words that are generated by paths in G .
- The capacity of S is given by

$$\text{cap}(S) = \lim_{\ell \rightarrow \infty} (1/\ell) \cdot \log_2 |S \cap \Sigma^\ell| .$$

Parallel Encoding

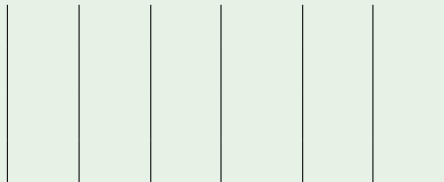
An M -track, rate R , parallel encoder for a constraint $S \subseteq \Sigma^*$

- We write to M tracks (columns).

Parallel Encoding

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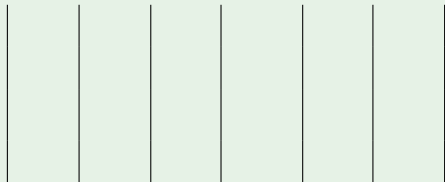
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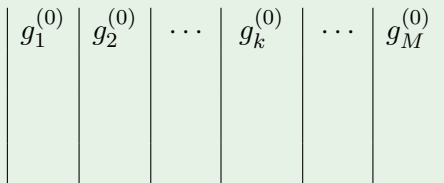
- We write to M tracks (columns).
- At each time slot, a symbol is written to each track (we produce a row).
- The row written is a function of the state of the encoder and of the current $M \cdot R$ information bits.



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$$\begin{array}{c}
 \left| \begin{array}{c} g_1^{(0)} \\ g_1^{(1)} \end{array} \right| \left| \begin{array}{c} g_2^{(0)} \\ g_2^{(1)} \end{array} \right| \left| \begin{array}{c} \cdots \\ \cdots \end{array} \right| \left| \begin{array}{c} g_k^{(0)} \\ g_k^{(1)} \end{array} \right| \left| \begin{array}{c} \cdots \\ \cdots \end{array} \right| \left| \begin{array}{c} g_M^{(0)} \\ g_M^{(1)} \end{array} \right|
 \end{array}$$

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$$\begin{array}{c}
 \left| \begin{array}{c} g_1^{(0)} \\ g_1^{(1)} \\ \vdots \\ g_1^{(t)} \end{array} \right| \left| \begin{array}{c} g_2^{(0)} \\ g_2^{(1)} \\ \vdots \\ g_2^{(t)} \end{array} \right| \left| \begin{array}{c} \cdots \\ \cdots \\ \cdots \\ \cdots \end{array} \right| \left| \begin{array}{c} g_k^{(0)} \\ g_k^{(1)} \\ \vdots \\ g_k^{(t)} \end{array} \right| \left| \begin{array}{c} \cdots \\ \cdots \\ \cdots \\ \cdots \end{array} \right| \left| \begin{array}{c} g_M^{(0)} \\ g_M^{(1)} \\ \vdots \\ g_M^{(t)} \end{array} \right|
 \end{array}$$

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- Each track must contain an element of S .

$$\begin{array}{c}
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 \end{array}$$

Parallel Decoding

An M -track (m, a) -SBD decoder

- At time slot t , the respective input bits are recovered from rows $t - m, t - m + 1, \dots, t + a$

$$\begin{array}{cccccc}
 \vdots & \vdots & \dots & \vdots & \dots & \vdots \\
 g_1^{(t-m)} & g_2^{(t-m)} & \dots & g_k^{(t-m)} & \dots & g_M^{(t-m)} \\
 \vdots & \vdots & \dots & \vdots & \dots & \vdots \\
 g_1^{(t)} & g_2^{(t)} & \dots & g_k^{(t)} & \dots & g_M^{(t)} \\
 \vdots & \vdots & \dots & \vdots & \dots & \vdots \\
 g_1^{(t+a)} & g_2^{(t+a)} & \dots & g_k^{(t+a)} & \dots & g_M^{(t+a)} \\
 \vdots & \vdots & \dots & \vdots & \dots & \vdots
 \end{array}$$

Main Results

Main results of our parallel encoding/decoding scheme

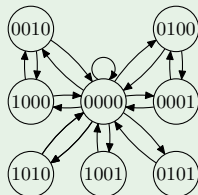
- We approach $\text{cap}(S(G))$ as the number of tracks, M , grows.
- The vertical size of the decoding window is constant in M .
- For a constant graph size, encoding and decoding time is $O(M \log^2 M \log \log M)$.

2-D Constraints

- Consider as an example the square constraint [WeeksBlahut98]:
- The elements are all the binary arrays in which an entry may equal '1' only if all its eight neighbors are '0'.

$$\begin{array}{cccc}
 1 & 0 & 0 & 1 \\
 0 & 0 & 0 & 0 \\
 0 & 1 & 0 & 0 \\
 0 & 0 & 0 & 1
 \end{array}$$

- A graph which produces *all* $\ell \times 4$ arrays that satisfy this constraint:
- Thus, if the number of columns is reasonably small, we can reduce our 2-D constraint to a 1-D constraint.



The label of an edge is given by the label of the vertex it exits.

2-D Constraints (Cont.)

- We use this as follows:
- Partition the 2-D array into two alternating type strips:

$$\begin{array}{cccc|c|cccc|c|cccc} 0 & 0 & 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 \end{array}$$

2-D Constraints (Cont.)

- We use this as follows:
- Partition the 2-D array into two alternating type strips:
 - M data strips of width 4.

$$\begin{array}{cccc|c|cccc|c|cccc}
 0 & 0 & 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 1 \\
 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 \\
 0 & 0 & 0 & 1 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0 & 0 & 0
 \end{array}$$

2-D Constraints (Cont.)

- We use this as follows:
- Partition the 2-D array into two alternating type strips:
 - M data strips of width 4.
 - $M - 1$ merging strips of width 1.

0	0	1	0	0	1	0	1	0	0	0	0	0	1
1	0	0	0	0	0	0	0	0	0	1	0	0	0
0	0	0	1	0	0	1	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	0	0	0	0	0

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1	0	0	0	0	0	0	0	0	0	1	0	0	0
0	0	0	1	0	0	1	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	0	0	0	0	0

- Think of each of the data strips as a track.

2-D Constraints (Cont.)

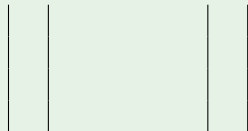
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1	0	0	0	0	0	0	0	0	0	1	0	0	0
0	0	0	1	0	0	1	0	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	0	0	0	0	0

- Think of each of the data strips as a track.
- Fill all the merging strips with '0' bits.

2-D Constraints (Cont.)

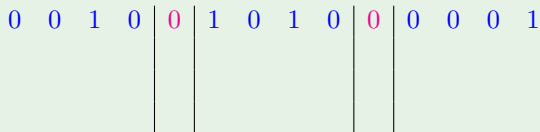
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- Fill all the merging strips with '0' bits.
- We may now use an M -track parallel encoder in order to encode information to the array in a row-by-row manner.

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$$\begin{array}{cccc|c|cccc|c|cccc}
 0 & 0 & 1 & 0 & 0 & 1 & 0 & 1 & 0 & 0 & 0 & 0 & 1 \\
 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & 1 & 0 & 0 & 0
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0	0	0	1	0	0	1	0	0	0	0	0	0	0

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0	0	0	1	0	0	1	0	0	0	0	0	0
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0	0	0	1	0	0	1	0	0	0	0	0	0
1	0	0	0	0	0	0	0	1	0	0	0	0

- Think of each of the data strips as a track.
- Fill all the merging strips with '0' bits.
- We may now use an M -track parallel encoder in order to encode information to the array in a row-by-row manner.
- Enlarging the width of the data strips gives a better encoding rate, at the expense of the encoder's complexity.

Encoder Definition

Multiplicity Matrix

- The description of our M -track parallel encoder for $S = S(G)$ is defined by its respective **multiplicity matrix** D :
- Let $A_G = (a_{i,j})$ be the adjacency matrix of G .
- A nonnegative integer matrix $D = (d_{i,j})_{i,j \in V}$ is a valid multiplicity matrix with respect to G and M if

$$\mathbf{1} \cdot D \cdot \mathbf{1}^T \leq M, \quad (1)$$

$$\mathbf{1} \cdot D = \mathbf{1} \cdot D^T, \quad \text{and} \quad (2)$$

$$d_{i,j} > 0 \text{ only if } a_{i,j} > 0. \quad (3)$$

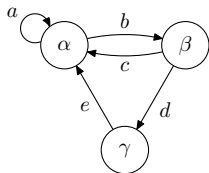
- Our aim is to find a multiplicity matrix such that the respective encoder has rate close to $\text{cap}(S)$.

- For the sake of exposition, assume that G does not contain parallel edges.
- Let $\mathcal{P}_D : E \rightarrow [0, 1]$ be the Markov chain on G defined as follows:

$$\mathcal{P}_D(i \rightarrow j) = d_{i,j} / (\mathbf{1} \cdot D \cdot \mathbf{1}^T) .$$

- Since we required that $\mathbf{1} \cdot D = \mathbf{1} \cdot D^T$, we have that \mathcal{P}_D is *stationary*.
- Essentially, the encoder “mimics” \mathcal{P}_D .
- The rate of the encoder approaches $\text{cap}(S)$ when $\mathbf{1} \cdot D \cdot \mathbf{1}^T$ approaches M and \mathcal{P}_D is close to the maxentropic Markov chain on G .

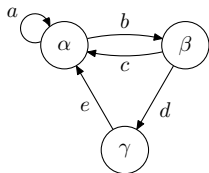
Encoder Example



$$A_G = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \quad D = \begin{pmatrix} 4 & 3 & 0 \\ 2 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$M = 12$$

Encoder Example

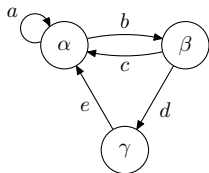


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- $1 \cdot D \cdot 1^T = 11$

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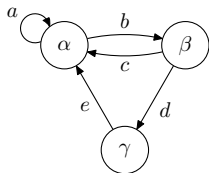


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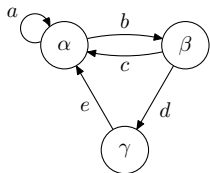


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- $\mathbf{1} \cdot D \cdot \mathbf{1}^T = 11$
- $\mathbf{1} \cdot D^T = (7, 3, 1)$

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Encoder Example



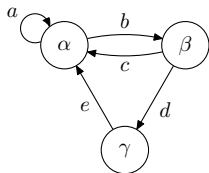
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α	α	α	α	α	α	α							
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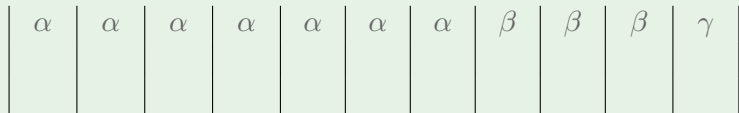
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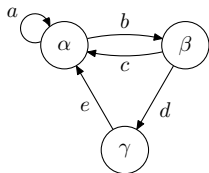
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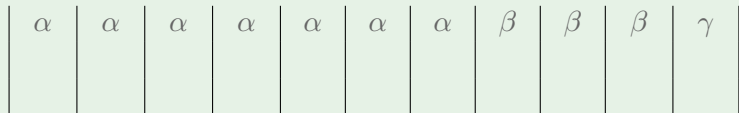
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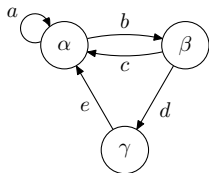
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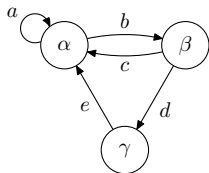
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α	α	α	α	α	α	α	β	β	β	γ
$a \downarrow$	$a \downarrow$	$a \downarrow$	$a \downarrow$							
α	α	α	α							

Encoder Example



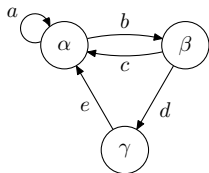
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- $\mathbf{1} \cdot D \cdot \mathbf{1}^T = 11$
- $\mathbf{1} \cdot D^T = (7, 3, 1)$

$$M = 12$$

α	α	α	α	α	α	α	β	β	β	γ
$a \downarrow$	$a \downarrow$	$a \downarrow$	$a \downarrow$	$b \downarrow$	$b \downarrow$	$b \downarrow$				
α	α	α	α	β	β	β				

Encoder Example



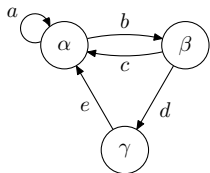
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- $\mathbf{1} \cdot D \cdot \mathbf{1}^T = 11$
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α	α	α	α	α	α	α	β	β	β	γ
$a \downarrow$	$a \downarrow$	$a \downarrow$	$a \downarrow$	$b \downarrow$	$b \downarrow$	$b \downarrow$	$c \downarrow$	$c \downarrow$	$d \downarrow$	$e \downarrow$
α	α	α	α	β	β	β	α	α	γ	α

Encoder Example



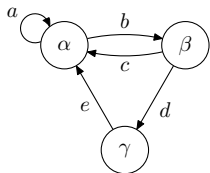
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- $\mathbf{1} \cdot D \cdot \mathbf{1}^T = 11$
- $\mathbf{1} \cdot D^T = (7, 3, 1) = \mathbf{1} \cdot D$

$$M = 12$$

α	α	α	α	α	α	α	β	β	β	γ
$a \downarrow$	$a \downarrow$	$a \downarrow$	$a \downarrow$	$b \downarrow$	$b \downarrow$	$b \downarrow$	$c \downarrow$	$c \downarrow$	$d \downarrow$	$e \downarrow$
α	α	α	α	β	β	β	α	α	γ	α

Encoder Example



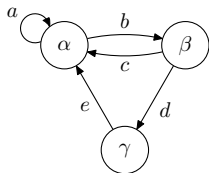
$$A_G = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix} \quad D = \begin{pmatrix} 4 & 3 & 0 \\ 2 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

- $\mathbf{1} \cdot D \cdot \mathbf{1}^T = 11$
- $\mathbf{1} \cdot D^T = (7, 3, 1) = \mathbf{1} \cdot D$

$$M = 12$$

α	α	α	α	α	α	α	β	β	β	γ
$a \downarrow$	$a \downarrow$	$a \downarrow$	$a \downarrow$	$b \downarrow$	$b \downarrow$	$b \downarrow$	$c \downarrow$	$c \downarrow$	$d \downarrow$	$e \downarrow$
α	α	α	α	β	β	β	α	α	γ	α

Encoder Example



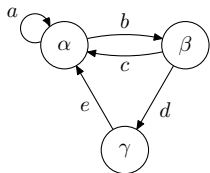
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Encoder Example



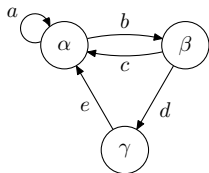
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Encoder Example



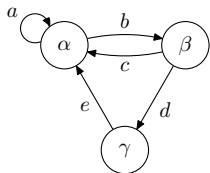
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α	α	α	α	β	β	β	α	γ	α	α

Encoder Example



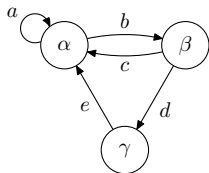
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Encoder Example



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- $\mathbf{1} \cdot D \cdot \mathbf{1}^T = 11$
- $\mathbf{1} \cdot D^T = (7, 3, 1) = \mathbf{1} \cdot D$
- $\Delta = \left(\prod_{i \in V} r_i! \right) / \left(\prod_{i,j \in V} d_{i,j}! \cdot a_{i,j}^{-d_{i,j}} \right)$

$$M = 12$$

α	α	α	α	α	α	α	β	β	β	γ
$a \downarrow$	$a \downarrow$	$a \downarrow$	$a \downarrow$	$b \downarrow$	$b \downarrow$	$b \downarrow$	$d \downarrow$	$c \downarrow$	$c \downarrow$	$e \downarrow$
α	α	α	α	β	β	β	γ	α	α	α

Maxentropic Distribution

- Let $\mathcal{P}^* : E \rightarrow [0, 1]$ be the maxentropic stationary Markov chain on G .
- For an as yet unspecified M' , define:

$$P = (p_{i,j}) , p_{i,j} = M' \mathcal{P}^*(i \rightarrow j) .$$

Halevy and Roth's Solution

- If, when taking $M' = M$, all the entries of P were **integers**, then we could take $D = P$.
- We would have $R(D) = \frac{\log_2 \Delta}{M} \xrightarrow{M \rightarrow \infty} \text{cap}(S(G))$.
- Solution [HalevyRoth]: Perturb a related matrix such that its entries are rational, and take $M = M'$ large enough.
- Problem: M unrealistically large.

- Take $M' = M - \lfloor |V| \text{diam}(G)/2 \rfloor$.
- We say that an *integer* matrix $\tilde{P} = (\tilde{p}_{i,j})$ is a **good quantization** of $P = (p_{i,j})$ if

$$M' = \sum_{i,j \in V} p_{i,j} = \sum_{i,j \in V} \tilde{p}_{i,j} , \quad (4)$$

$$\left\lfloor \sum_{j \in V} p_{i,j} \right\rfloor \leq \sum_{j \in V} \tilde{p}_{i,j} \leq \left\lceil \sum_{j \in V} p_{i,j} \right\rceil , \quad (5)$$

$$\lfloor p_{i,j} \rfloor \leq \tilde{p}_{i,j} \leq \lceil p_{i,j} \rceil , \quad \text{and—} \quad (6)$$

$$\left\lfloor \sum_{i \in V} p_{i,j} \right\rfloor \leq \sum_{i \in V} \tilde{p}_{i,j} \leq \left\lceil \sum_{i \in V} p_{i,j} \right\rceil . \quad (7)$$

Lemma

There exists a matrix \tilde{P} which is a good quantization of P . Furthermore, such a matrix can be found by an efficient algorithm.

Partial Proof.

- Formulate the above as an **integer flow problem**.
- A *fractional* solution exists.
- Thus, an integer solution exists. □

Example

$$M = 12$$

$$A_G = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

Example

$$M = 12 \quad M' = 9$$

$$A_G = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

Example

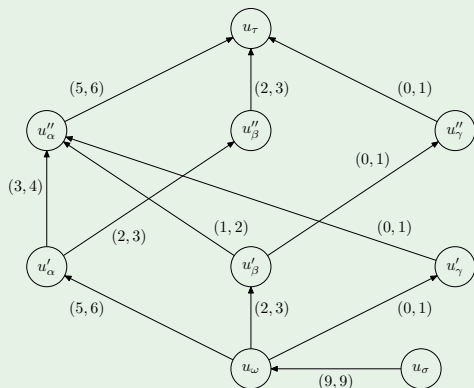
$$M = 12 \quad M' = 9$$

$$A_G = \begin{pmatrix} 1 & 1 & 0 \\ 1 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}$$

$$P = \begin{pmatrix} 3.05 & 2.53 & 0 \\ 1.64 & 0 & 0.89 \\ 0.89 & 0 & 0 \end{pmatrix}$$

$$\tilde{P} = \begin{pmatrix} 4 & 2 & 0 \\ 2 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

Example



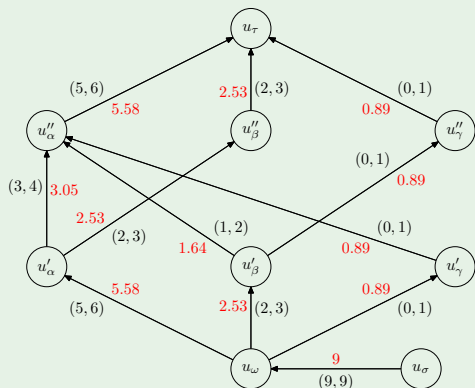
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Example



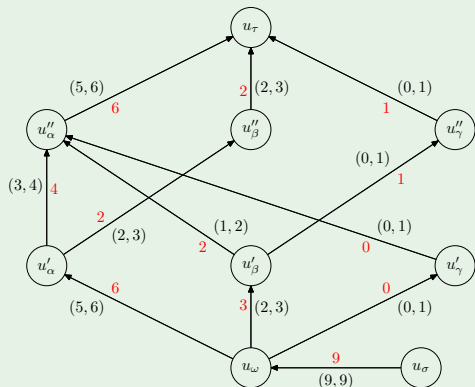
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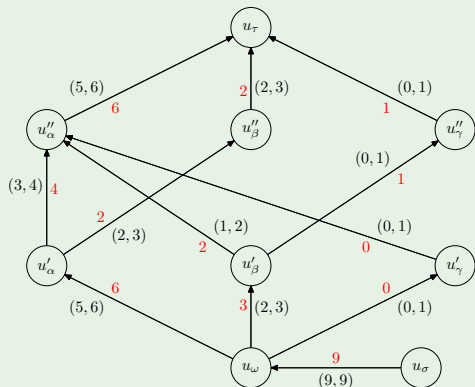
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$$\tilde{P} = \begin{pmatrix} 4 & 2 & 0 \\ 2 & 0 & 1 \\ 0 & 0 & 0 \end{pmatrix}$$

- \tilde{P} is an integer matrix (a good quantization of P).
- However, \tilde{P} is generally not a valid multiplicity matrix:
- We might have that $\mathbf{1} \cdot (\tilde{P})^T \neq \mathbf{1} \cdot \tilde{P}$ (the respective Markov chain is not stationary).

Theorem

Let $\tilde{P} = (\tilde{p}_{i,j})$ be a good quantization of P . There exists a multiplicity matrix $D = (d_{i,j})$ with respect to G and M , such that

- 1 $d_{i,j} \geq \tilde{p}_{i,j}$ for all $i, j \in V$, and—
- 2 $M' - \lfloor |V| \text{diam}(G)/2 \rfloor \leq \mathbf{1} \cdot D \cdot \mathbf{1}^T \leq M$

(where $M' = M - \lfloor |V| \text{diam}(G)/2 \rfloor$). Moreover, the matrix D can be found by an efficient algorithm.

Proof makes use of network flow as well.

Main Theorem

Theorem

Let G be a deterministic graph with memory m . For M sufficiently large, one can efficiently construct an M -track $(m, 0)$ -SBD parallel encoder for $S = S(G)$ at a rate R such that

$$R \geq \text{cap}(S(G)) \left(1 - \frac{|V| \text{diam}(G)}{2M} \right) - O \left(\frac{|V|^2 \log(M \cdot a_{\max}/a_{\min})}{M - |V| \text{diam}(G)/2} \right),$$

where a_{\min} (respectively, a_{\max}) is the smallest (respectively, largest) nonzero entry in A_G .

Proof makes use of the multiplicity matrix guaranteed by previous theorem.