

The Andrew & Erna Viterbi **Faculty of Electrical Engineering** Electronics ■■■■Computers Communications



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Signal Acquisition Modeling and Processing Lab

# **Xampling-Enabled Coexistence in Spectrally Crowded Environments**

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David Cohen

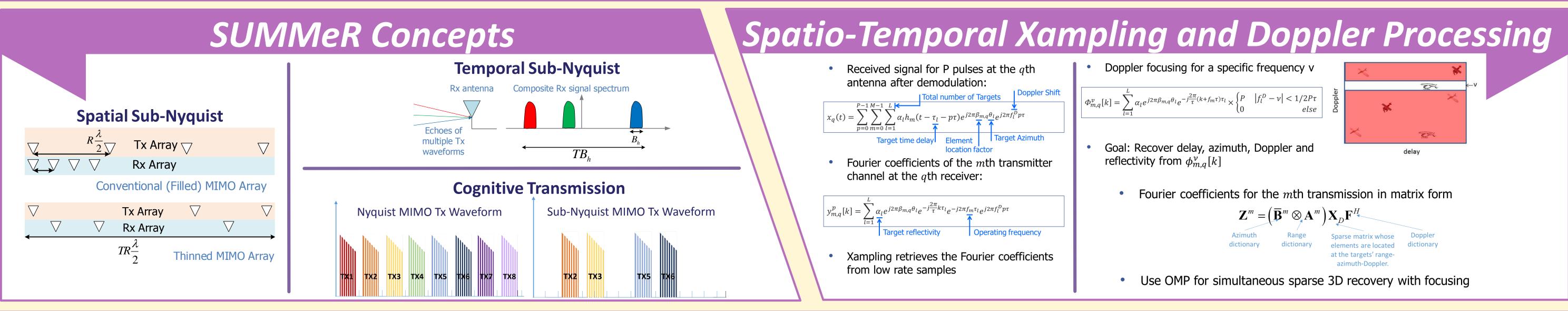
Shahar Tsiper Ron Madmoni Eran Ronen

Shahar Stein Yana Grimovich

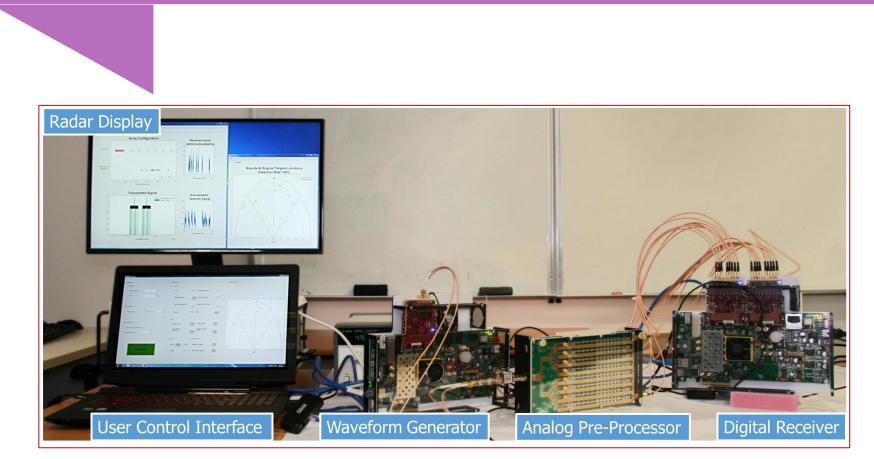
Eli Shoshan Andrey Zhitnikov

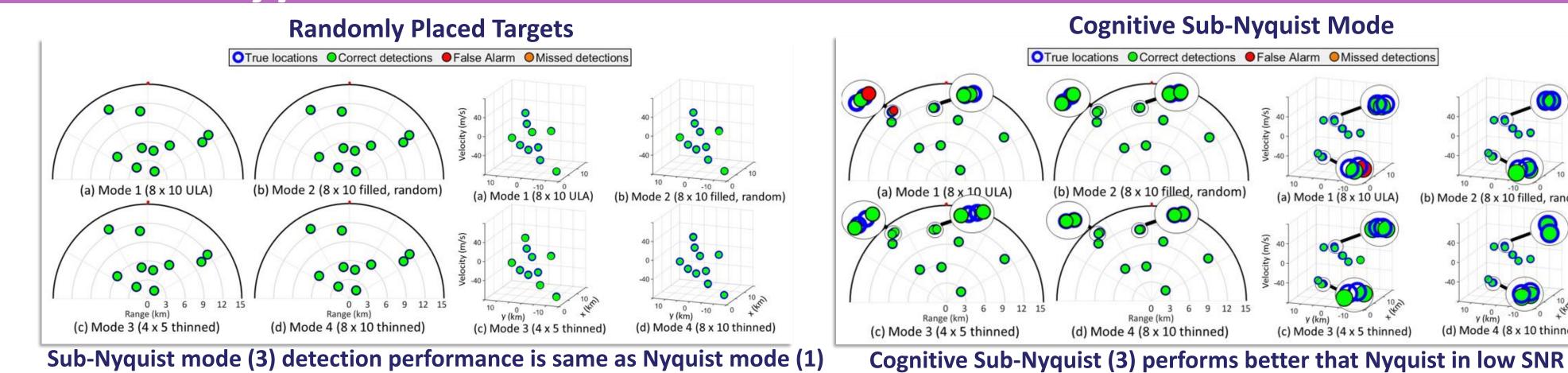
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# Cognitive Sub-Nyquist MIMO Radar (SUMMeR)



#### Hardware Prototype and Measurement Results

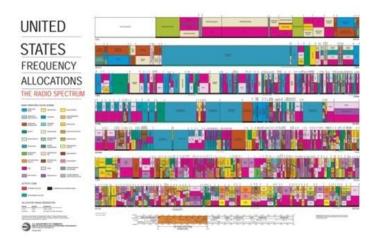


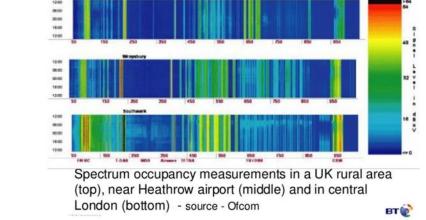


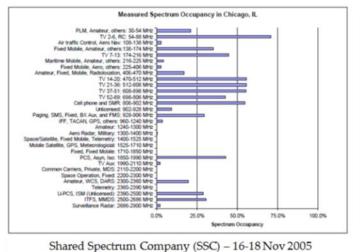
# **CompreSsed CArrier and Direction-of-arrival Estimation (CaSCADE)**

### Cognitive Radio (CRo)

- Address the conflict between spectrum saturation and underutilization
- Grant opportunistic access to spectrum "holes" to unlicensed users
- Perform spectrum sensing task efficiently, in real-time and reliably

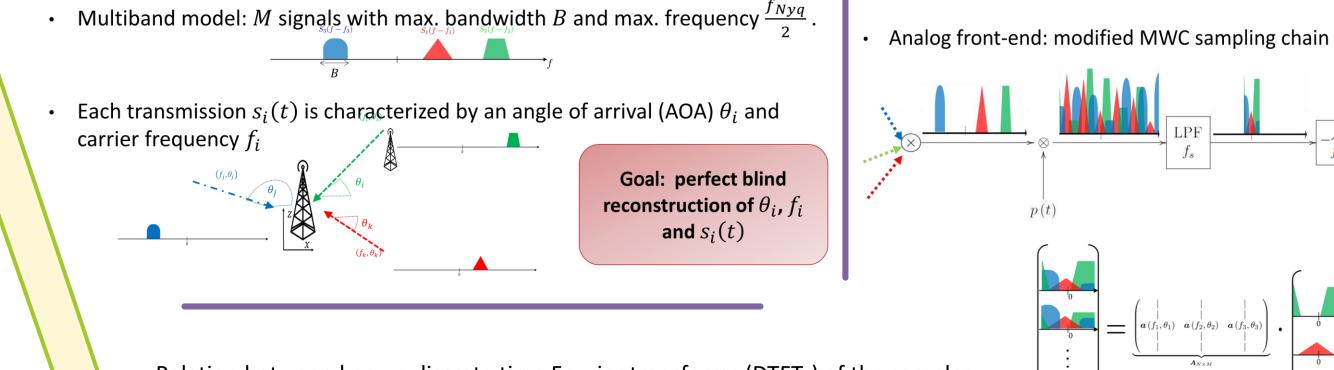






- Nyquist sampling is not an option  $\Rightarrow$  sub-Nyquist sampling
- Joint DOA estimation and spectrum sensing increase CR efficiency

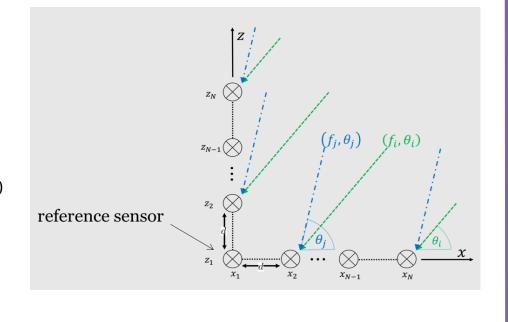
#### Signal Model and Sampling Scheme

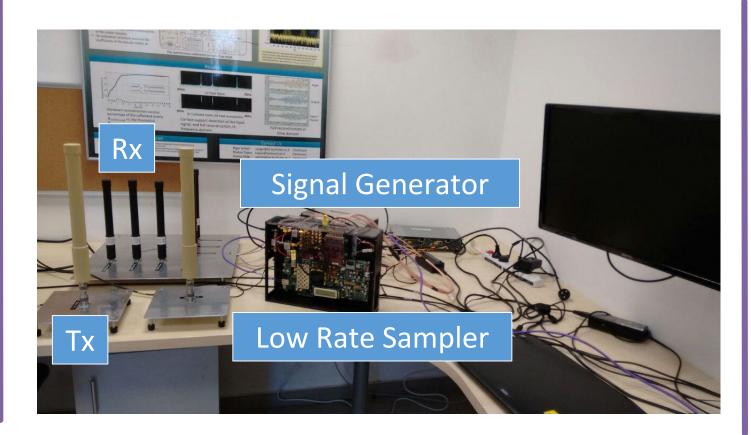


Relation between known discrete time Fourier transforms (DTFTs) of the samples from the ULA in x axis and unknown signal Fourier transform:

#### Algorithm, Hardware Prototype and Results

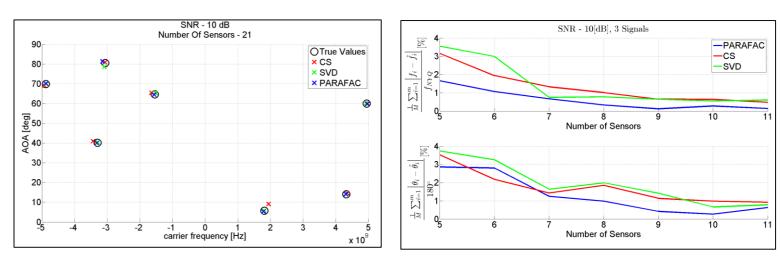
- L-shape ULA with N sensors in x axis and N + 1 sensors in z axis:
- $\Delta \phi_{X_n} \left( f_i, \theta_i \right) = \frac{2\pi d}{m} \cdot n \cdot f_i \cos\left(\theta_i\right)$ • Phase accumulation in *x* axis:
- $\Delta \phi_{Z_n} \left( f_i, \theta_i \right) = \frac{2\pi d}{d} \cdot n \cdot f_i \sin \left( \theta_i \right)$ • Phase accumulation in *z* axis:
- Received signal at n<sup>th</sup> sensor in x axis:  $U_n(f) = \sum_{i=1}^M S_i(f f_i)e^{j\Delta\phi_{X_n}(f_i,\theta_i)}$
- To overcome the pairing problem:
- Compute cross correlation matrices between ULAs
- Perform joint SVD on the cross-correlations
- Compute  $\theta_i$  and  $f_i$  from the paired eigenvalues





#### Compared methods:

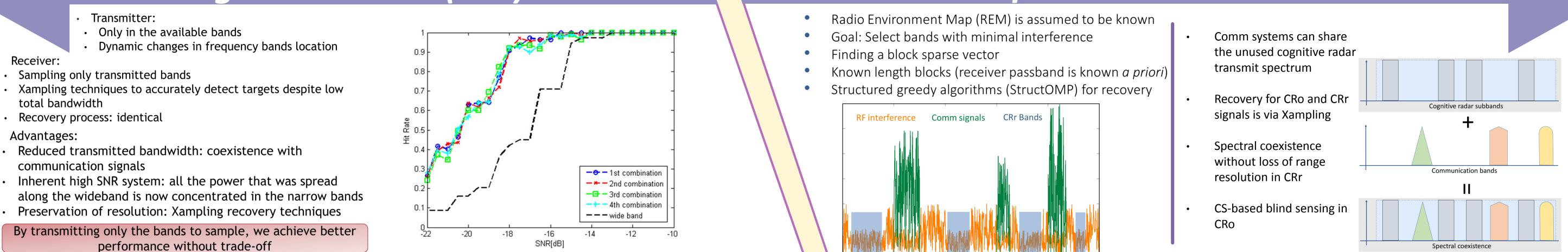
- **PARAFAC:** iterative algorithm (based on alternating least squares)
- Compressed sensing (CS): exploiting the spectrum sparsity
- Joint SVD ESPRIT (SVD): analytic solution (as presented)



## Spectral Coexistence via Xampling (SpeCX)

#### Cognitive Radar (CRr)

#### Spectral Coexistence



#### Hardware Prototype and Measurement Results

