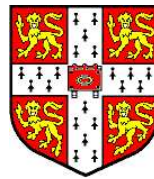


Augmented Statistical Models: Exploiting Generative Models in Discriminative Classifiers

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Overview

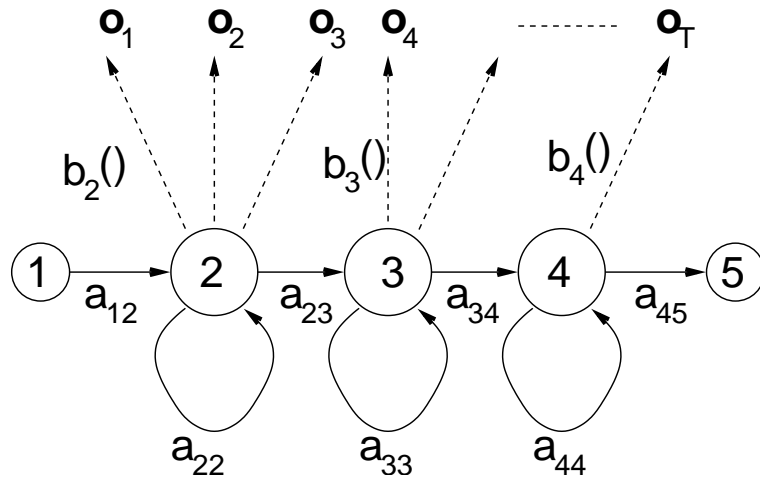
- Generative models in discriminative classifiers
 - Fisher score-space
 - Generative score-space
- Augmented Statistical Models
 - extension of standard models, e.g. GMMs and HMMs
 - allows additional dependencies to be represented
- Discriminative training
 - maximum margin
 - conditional maximum likelihood
- TIMIT results



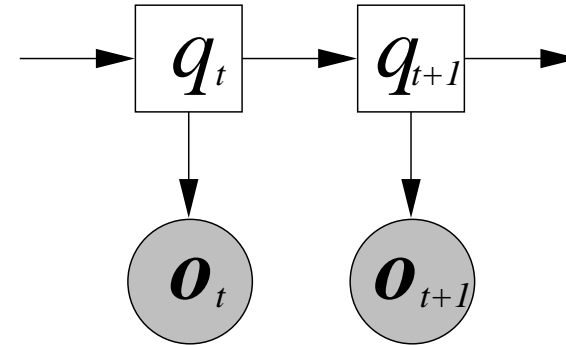
Generative Models in Discriminative Classifiers



The Hidden Markov Model



(a) Standard HMM phone topology



(b) HMM Dynamic Bayesian Network

- Observations conditionally independent of other observations given state.
- States conditionally independent of other states given previous states.
- **Poor model of the speech process - piecewise constant state-space.**

Fisher Score-spaces

- Jaakkola & Haussler (1999)
- Method of incorporating generative models within a discriminative framework
- Define a **base generative model** $\hat{p}(\mathbf{O}; \boldsymbol{\lambda})$
 - 1-dimensional log-likelihood
 - not enough information for good classification
- Instead use a **score-space** $\phi^{\text{F}}(\mathbf{O}; \boldsymbol{\lambda})$
 - tangent-space captures essence of generative process

$$\phi^{\text{F}}(\mathbf{O}; \boldsymbol{\lambda}) = \left[\nabla_{\boldsymbol{\lambda}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}) \right]$$

- dimensionality of score-space: parameters $\boldsymbol{\lambda}$
- suitable for discriminative training (SVMs, etc)
- has been applied to many tasks, e.g. comp. biology and speech recognition



Generative Score-spaces

- Smith & Gales (2002)
- Extension for supervised binary classification tasks
- Define **class-conditional base models** $\hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(1)})$ and $\hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(2)})$
 - includes log-likelihood ratio to improve discrimination
 - avoids wrap-around (different \mathbf{O} 's map to the same point in score-space)
- **Score-space** $\phi^{\text{LL}}(\mathbf{O}; \boldsymbol{\lambda})$

$$\phi^{\text{LL}}(\mathbf{O}; \boldsymbol{\lambda}) = \begin{bmatrix} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(1)}) - \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(2)}) \\ \nabla_{\boldsymbol{\lambda}^{(1)}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(1)}) \\ -\nabla_{\boldsymbol{\lambda}^{(2)}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(2)}) \end{bmatrix}$$

- suitable for discriminative training — SVMs
- no probabilistic interpretation
- restricted to binary problems



Augmented Statistical Models



Dependency Modelling

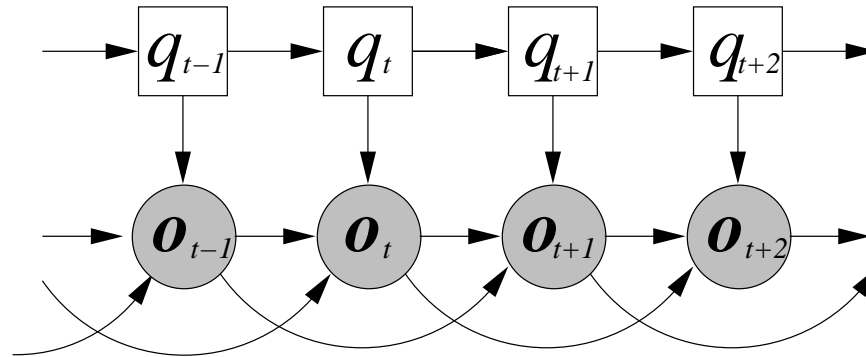
- Speech data is dynamic — observations are not of a fixed length
- Dependency modelling essential part of speech recognition

$$p(\mathbf{o}_1, \dots, \mathbf{o}_T; \boldsymbol{\lambda}) = p(\mathbf{o}_1; \boldsymbol{\lambda})p(\mathbf{o}_2|\mathbf{o}_1; \boldsymbol{\lambda}) \dots p(\mathbf{o}_T|\mathbf{o}_1, \dots, \mathbf{o}_{T-1}; \boldsymbol{\lambda})$$

- impractical to directly model in this form
- make extensive use of conditional independence
- Two possible forms of conditional independence
 - latent (unobserved) variables
 - observed variables
- Even if given a set of dependencies (form of Bayesian Network)
 - need to determine how dependencies interact



Dependency Modelling



- Commonly use a member (or mixture) of the **exponential family**

$$p(\mathbf{O}; \boldsymbol{\alpha}) = \frac{1}{\tau(\boldsymbol{\alpha})} h(\mathbf{O}) \exp(\boldsymbol{\alpha}^T \mathbf{T}(\mathbf{O}))$$

$h(\mathbf{O})$ is the **reference distribution**

τ is the **normalisation term**

$\boldsymbol{\alpha}$ are the **natural parameters**

$\mathbf{T}(\mathbf{O})$ are **sufficient statistics**

- What is the appropriate form of statistics ($\mathbf{T}(\mathbf{O})$)?

– for diagram above, $\mathbf{T}(\mathbf{O}) = \sum_{t=1}^{T-2} \mathbf{o}_t \mathbf{o}_{t+1} \mathbf{o}_{t+2}$



Augmented Statistical Models

- Augmented statistical models (related to **fibre bundles**)

$$p(\mathbf{O}; \boldsymbol{\lambda}, \boldsymbol{\alpha}) = \frac{1}{\tau(\boldsymbol{\lambda}, \boldsymbol{\alpha})} \hat{p}(\mathbf{O}; \boldsymbol{\lambda}) \exp \left(\boldsymbol{\alpha}^T \begin{bmatrix} \nabla_{\boldsymbol{\lambda}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}) \\ \frac{1}{2!} \text{vec}(\nabla_{\boldsymbol{\lambda}}^2 \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda})) \\ \vdots \\ \frac{1}{\rho!} \text{vec}(\nabla_{\boldsymbol{\lambda}}^{\rho} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda})) \end{bmatrix} \right)$$

- Two sets of parameters:
 - $\boldsymbol{\lambda}$ - parameters of base distribution ($\hat{p}(\mathbf{O}; \boldsymbol{\lambda})$)
 - $\boldsymbol{\alpha}$ - natural parameters of local exponential model
- Normalisation term $\tau(\boldsymbol{\lambda}, \boldsymbol{\alpha})$ ensures valid PDF

$$\int p(\mathbf{O}; \boldsymbol{\lambda}, \boldsymbol{\alpha}) d\mathbf{O} = 1; \quad p(\mathbf{O}; \boldsymbol{\lambda}, \boldsymbol{\alpha}) = \frac{\bar{p}(\mathbf{O}; \boldsymbol{\lambda}, \boldsymbol{\alpha})}{\tau(\boldsymbol{\lambda}, \boldsymbol{\alpha})}$$

- can be very difficult to estimate

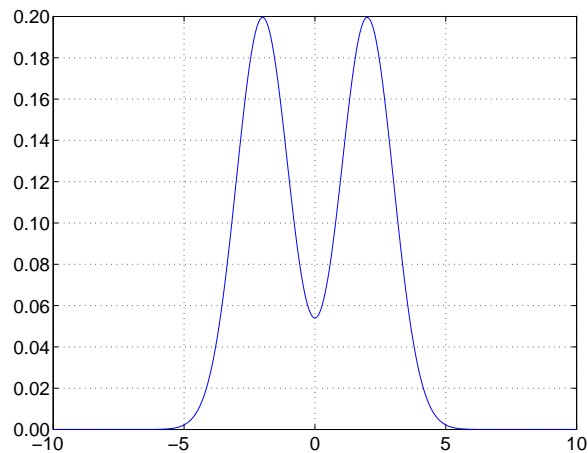


Example: Augmented GMM

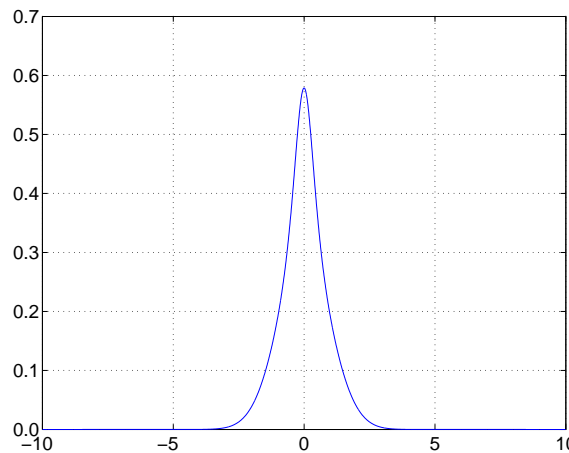
- Use a GMM as the base distribution: $\hat{p}(\mathbf{o}; \boldsymbol{\lambda}) = \sum_{m=1}^M c_m \mathcal{N}(\mathbf{o}; \boldsymbol{\mu}_m, \boldsymbol{\Sigma}_m)$

$$p(\mathbf{o}; \boldsymbol{\lambda}, \boldsymbol{\alpha}) = \frac{1}{\tau} \sum_{m=1}^M c_m \mathcal{N}(\mathbf{o}; \boldsymbol{\mu}_m, \boldsymbol{\Sigma}_m) \exp \left(\sum_{n=1}^M P(n|\mathbf{o}; \boldsymbol{\lambda}) \boldsymbol{\alpha}_n^T \boldsymbol{\Sigma}_n^{-1} (\mathbf{o} - \boldsymbol{\mu}_n) \right)$$

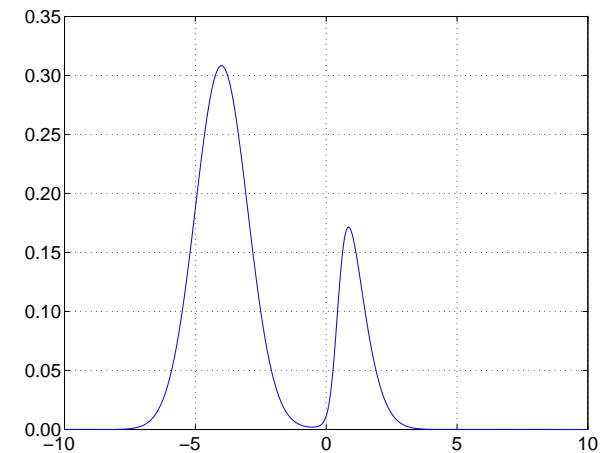
- Simple two component one-dimensional example:



$$\boldsymbol{\alpha} = [0.0, 0.0]^T$$



$$\boldsymbol{\alpha} = [-1.0, -1.0]^T$$



$$\boldsymbol{\alpha} = [1.0, -1.0]^T$$



Augmented Model Dependencies

- If the base distribution is a latent-variable model — GMM, HMM, ...
 - Sufficient statistics contain a first-order differential

$$\nabla_{\boldsymbol{\mu}_{jm}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}) = \sum_{t=1}^T P(\theta_t = \{s_j, m\} | \mathbf{O}; \boldsymbol{\lambda}) \boldsymbol{\Sigma}_{jm}^{-1} (\mathbf{O}_t - \boldsymbol{\mu}_{jm})$$

- depends on a **posterior**
 - compact representation of effects of all observations
- Augmented models of this form:
 - **retain independence assumptions** of the base model
 - **remove conditional independence assumptions** of the base model...
... since the local exponential model depends on a posterior
- For HMM base models,
 - observations are dependent on **all observations** and **all latent states**
 - higher-order derivatives create increasingly powerful models



Discriminative Training



Maximum Margin Estimation

- Consider the simplified **two-class** problem
- Bayes' decision rule (consider λ fixed)

$$\frac{P(\omega_1|\mathbf{O})}{P(\omega_2|\mathbf{O})} = \frac{P(\omega_1)\tau(\boldsymbol{\lambda}^{(2)}, \boldsymbol{\alpha}^{(2)})\bar{p}(\mathbf{O}; \boldsymbol{\lambda}^{(1)}, \boldsymbol{\alpha}^{(1)})}{P(\omega_2)\tau(\boldsymbol{\lambda}^{(1)}, \boldsymbol{\alpha}^{(1)})\bar{p}(\mathbf{O}; \boldsymbol{\lambda}^{(2)}, \boldsymbol{\alpha}^{(2)})} \begin{matrix} \omega_1 \\ > \\ \omega_2 \end{matrix} \begin{matrix} \\ \\ 1 \end{matrix}$$

– class priors $P(\omega_1)$ and $P(\omega_2)$

- Can be rewritten as a **linear decision boundary** in a **generative score-space**,

$$\underbrace{\frac{1}{T} \ln \left(\frac{\bar{p}(\mathbf{O}; \boldsymbol{\lambda}^{(1)}, \boldsymbol{\alpha}^{(1)})}{\bar{p}(\mathbf{O}; \boldsymbol{\lambda}^{(2)}, \boldsymbol{\alpha}^{(2)})} \right)}_{\mathbf{w}^T \boldsymbol{\phi}^{\text{LL}}(\mathbf{O}; \boldsymbol{\lambda})} + \underbrace{\frac{1}{T} \ln \left(\frac{P(\omega_1)\tau(\boldsymbol{\lambda}^{(2)}, \boldsymbol{\alpha}^{(2)})}{P(\omega_2)\tau(\boldsymbol{\lambda}^{(1)}, \boldsymbol{\alpha}^{(1)})} \right)}_b \begin{matrix} \omega_1 \\ > \\ \omega_2 \end{matrix} 0$$

– no need to explicitly calculate $\tau(\boldsymbol{\lambda}^{(1)}, \boldsymbol{\alpha}^{(1)})$ or $\tau(\boldsymbol{\lambda}^{(2)}, \boldsymbol{\alpha}^{(2)})$

- Note: restrictions on α 's required to ensure a valid PDF



Maximum Margin Estimation (cont.)

- First-order **Generative score-space** given by

$$\phi^{\text{LL}}(\mathbf{O}; \boldsymbol{\lambda}) = \frac{1}{T} \begin{bmatrix} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(1)}) - \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(2)}) \\ \nabla_{\boldsymbol{\lambda}^{(1)}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(1)}) \\ -\nabla_{\boldsymbol{\lambda}^{(2)}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}^{(2)}) \end{bmatrix}$$

– independent of augmented parameters $\boldsymbol{\alpha}$

- **Linear decision boundary** specified by

$$\mathbf{w}^T = \begin{bmatrix} 1 & \boldsymbol{\alpha}^{(1)T} & \boldsymbol{\alpha}^{(2)T} \end{bmatrix}^T$$

– only a function of the exponential model parameters $\boldsymbol{\alpha}$

- **Bias** calculated as a by-product of training — depends on both $\boldsymbol{\alpha}$ and $\boldsymbol{\lambda}$
- Potentially many parameters to estimate:
 - maximum margin estimation (MME) good choice — SVM training



Conditional Augmented Models

- Often impossible to calculate normalisation term for generative augmented models
 - restricted to binary tasks
 - cannot use direct training
- Instead, consider **conditional augmented models**

$$p(\omega_j | \mathbf{O}; \boldsymbol{\lambda}, \boldsymbol{\alpha}) = \frac{1}{Z(\boldsymbol{\lambda}, \boldsymbol{\alpha})} \hat{p}(\mathbf{O}; \boldsymbol{\lambda}) \exp \left(\boldsymbol{\alpha}^T \begin{bmatrix} \nabla_{\boldsymbol{\lambda}} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda}) \\ \frac{1}{2!} \text{vec}(\nabla_{\boldsymbol{\lambda}}^2 \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda})) \\ \vdots \\ \frac{1}{\rho!} \text{vec}(\nabla_{\boldsymbol{\lambda}}^{\rho} \ln \hat{p}(\mathbf{O}; \boldsymbol{\lambda})) \end{bmatrix} \right)$$

- directly model **decision surfaces** between classes
- normalisation calculated as expectation over classes — easy to calculate



Conditional Maximum Likelihood Estimation

- Maximum likelihood of conditional model

$$\{\tilde{\lambda}, \tilde{\alpha}\} = \operatorname{argmax}_{\lambda, \alpha} \sum_{i=1}^n \ln P(y_i | \mathbf{O}_i; \lambda, \alpha)$$

- \mathbf{O}_i are training examples; y_i are class labels
- No closed-form solution

- Use stochastic gradient descent

- use noisy estimates of conditional log-likelihood gradient

$$\nabla_{\alpha} \ln P(y_i | \mathbf{O}_i; \lambda, \alpha) = \mathbf{T}(y_i, \mathbf{O}_i; \lambda) - \sum_{\omega \in \Omega} p(\omega | \mathbf{O}_i; \lambda, \alpha) \mathbf{T}(\omega, \mathbf{O}_i; \lambda)$$

- $\Omega = \{\omega_1, \dots, \}$ is the set of all class labels
- $\mathbf{T}(y_i, \mathbf{O}_i; \lambda)$ are the augmented model sufficient statistics
- optimisation is convex



TIMIT Results



TIMIT

- Phone classification task
- Training
 - 462 speakers: 3,696 sentences
 - 48 possible phones (classes)
- Testing
 - 24 speakers: 192 sentences
 - 48 phones mapped to a 39-class set for scoring purposes
- Data encoded using standard features: MFCC_0_D_A
 - 3 emitting state HMMs with 10 or 20 mixture components
 - first-order score-space: means, variances and component priors



TIMIT

Classifier	Criterion		Components	
	λ	α	10	20
HMM	ML	–	29.4	27.3
C-Aug	ML	CML	25.6	–
HMM	MMI	–	25.3	24.8
C-Aug	MMI	CML	24.1	–

- Conditional augmented models outperform HMMs
 - given a base model, it is better to augment it instead of increasing the number of mixture components
- Maximum-margin outperforms Conditional MLE (results not shown)
 - restricted to binary tasks
 - partly due to CML overtraining — regularisation required



Summary

- Augmented statistical models
 - allow complex dependencies to be added in a systematic fashion
 - breaks conditional independence assumptions of base model
 - simple to train using MM or CML estimation
- Preliminary results positive
 - outperform ML and MMI HMMs with similar numbers of parameters
 - CML optimisation is simple and easy to extend...
- Current work
 - Regularisation of CML
 - Updates of base model λ
 - Recognition

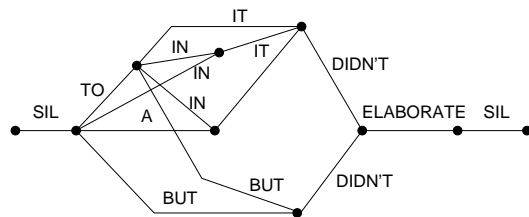


Extra Slides

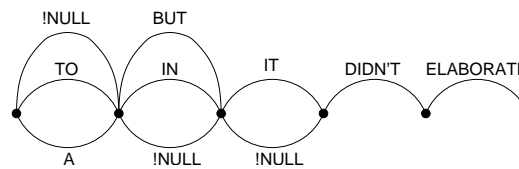


Binary Classifiers and LVCSR

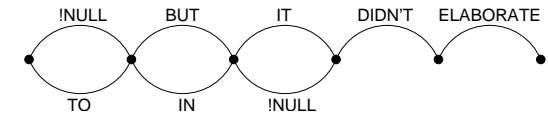
- Many classifiers (e.g. SVMs) are inherently binary:
 - speech recognition has a vast number of possible classes
 - how to map to a simple binary problem?
- Use **pruned confusion networks** (Venkataramani et al ASRU 2003):



Word lattice



Confusion Network



Pruned confusion network

- use standard HMM decoder to generate word lattice
- generate confusion networks (CN) from word lattice
 - gives posterior for each arc being correct;
- prune CN to a maximum of two arcs (based on posteriors).

8-Fold Cross-Validation LVCSR Results

Word Pair (Examples/class)	Classifier	Training		WER (%)
		Base (λ)	Aug (α)	
CAN/CAN'T (3761)	HMM	ML	—	11.0
		MMI	—	10.4
	A-HMM	ML	MM	9.5
KNOW/NO (4475)	HMM	ML	—	27.7
		MMI	—	27.1
	A-HMM	ML	MM	23.8

- A-HMM outperforms both ML and MMI HMM
 - also outperforms using “equivalent” number of parameters
 - difficult to split dependency modelling gains from change in training criterion



Evaluation Data LVCSR Results

- Baseline performance using Viterbi and Confusion Network decoding

Decoding	trigram LM
Viterbi	30.8
Confusion Network	30.1

- Rescore word-pairs using 3-state/4-component A-HMM+ β CN

SVM Rescoring	#corrected/#pairs	% corrected
10 SVMs	56/1250	4.5%

– only 1.6% of 76157 hypothesised words rescored - more SVMs required!

- More suitable to smaller tasks, e.g. digit recognition in low SNR conditions

